

MULTIPLICITIES OF EIGENVALUES AND TREE-WIDTH OF GRAPHS

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ABSTRACT. Using multiplicities of eigenvalues of elliptic self-adjoint differential operators on graphs and transversality, we construct some new invariants of graphs which are related to tree-width.

1. INTRODUCTION AND RESULTS

In this paper, we present some extensions of our invariant $\mu(G)$ for a finite graph $G = (V, E)$ which was introduced in [3].

Let us recall that $\mu(G)$ is defined using multiplicities of the second eigenvalue λ_2 of real symmetric matrices A related to G ($A \in O_G$, i.e. $a_{i,j} < 0$ if $\{i, j\} \in E$ and $a_{i,j} = 0$ if $i \neq j$ and $\{i, j\} \notin E$). For such an operator, the first eigenvalue (ground-state, λ_1) is non-degenerate if G is connected (Perron-Frobenius).

Moreover, $\mu(G)$ is related to the genus of G : $\mu(G) \leq 3$ if and only if G is planar; $\mu(G) \leq 4 \text{ genus}(G) + 3$. Recently, Lovasz and Schrijver [16] found that linklessly embeddable graphs are characterized by $\mu(G) \leq 4$.

What kind of extensions of these properties are valid for self-adjoint (complex) matrices related to G ? Such Hermitian matrices are obtained if we discretize Schrödinger operators with magnetic fields using the method of finite elements.

The eigenvalues of such operators can be very degenerate even for a Schrödinger operator H with constant magnetic field in the plane

$$H = -(\partial_x - iBy)^2 - \partial_y^2 ;$$

the spectrum of H , whose elements are called Landau levels in physics, is the set of eigenvalues $\sigma(H) = \{E_n = (2n + 1)|B| \mid n \in \mathbb{N}\}$. The eigenspaces $\ker(H - E_n)$ are infinite dimensional.

Therefore, we cannot expect some upper bound for multiplicities in terms of the genus of G , see [10].

The main idea of our paper is to compare G with a tree: if T is a tree and A is some self-adjoint elliptic operator on T , it is always possible to reduce to the case where $A \in O_T$ by some gauge transformation (conjugation by some diagonal unitary matrix); then the Perron-Frobenius theorem applies and shows that the ground-state is non-degenerate.

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For the other eigenvalues λ , we can consider $B = (A - \lambda)^2$ whose ground-state is 0 with eigenspace $\ker(A - \lambda)$. Of course B is no more a differential operator on T , but it is a differential operator on the graph $T^{(2)}$ ($V(T^{(2)}) = V(T)$, $E(T^{(2)}) = E(T) \cup \{\{i, j\}, i, j \in V(T) | \text{distance}(i, j) = 2\}$) whose tree-width $tw(T^{(2)})$ (see section 6) is bounded by 3, if all vertices of T have degree at most 3.

In all cases, we see that some trees are involved !!

Let us give more precise definitions and the main statements of the paper:

if $G = (V, E)$ is a finite undirected graph, without loops or multiple edges, we write $N = |V|$ and we will often index the vertices from 1 to N . Let n be some integer ≥ 1 and $\mathcal{H} = \mathcal{H}_{G,n} = \bigoplus_{i \in V} \mathbb{C}^n$ with the canonical Hilbert space structure. We will often consider elements of \mathcal{H} as functions from V to \mathbb{C}^n and use the notation $\varphi(i)$ for $\varphi \in \mathcal{H}$ and $i \in V$.

An endomorphism A of \mathcal{H} will be called an n -differential operator on G if $A = (A_{i,j})$, $(i, j) \in V \times V$ where the $A_{i,j}$'s are linear maps from \mathbb{C}^n to \mathbb{C}^n and $A_{i,j} = 0$ if $i \neq j$ and $\{i, j\} \notin E$.

A is *elliptic* if the $A_{i,j}$'s, $(\{i, j\} \in E)$ are invertible,

and *self-adjoint* if $\forall i, j, A_{i,j}^* = A_{j,i}$ (A^* denotes the adjoint of A).

Definition 1. Let us denote by $M_{G,n}$ the set (manifold) of all elliptic self-adjoint n -differential operators on G and $M_G = M_{G,1}$. We will denote by $R_G \subset M_G$ the subset of A 's with real coefficients and by $O_G \subset R_G$ the set of those $A = (a_{i,j})$ which satisfy

$$\forall \{i, j\} \in E, a_{i,j} < 0 .$$

For any $A \in M_{G,n}$, let us denote by $\lambda_1(A) \leq \lambda_2(A) \leq \dots \leq \lambda_{nN}(A)$ the ordered set of its eigenvalues repeated according to their multiplicities and by $\sigma(A) = \{\lambda_j(A), j = 1, \dots, nN\}$ the spectrum of A .

If $\lambda \in \mathbb{R}$, let us denote by $d(\lambda, A)$ (or $d(\lambda)$ if no ambiguity is possible) the dimension of $\ker(A - \lambda \text{Id})$.

The Perron-Frobenius theorem implies that, if G is connected, and $A \in O_G$, $d(\lambda_1(A)) = 1$.

Van der Holst proved in [13] the following extension to graphs of Cheng's theorem for manifolds [2]: if G is the 1-skeleton of some triangulation of the 2-sphere S^2 and $A \in O_G$, $d(\lambda_2(A), A) \leq 3$.

In the papers [18] and [19], Robertson and Seymour introduced the *tree-width* of a graph G , which we will denote by $tw(G)$.

We will use some slightly different definition which is more convenient for us :

Definition 2. If G is a finite graph, $la(G)$ is the smallest of those n for which G is a minor of $T \times K_n$ where T is some tree and K_n is the clique with n vertices (complete graph).

We have (see section 6):

Proposition 1. $tw(G)$ and $la(G)$ satisfy the following inequalities:

$$la(G) - 1 \leq tw(G) \leq 2la(G) - 1 .$$

We prove the following results:

Theorem 1. If $A \in M_{T,n}$ where T is a tree all of whose vertices have degree ≤ 3 , $d(\lambda_1(A), A) \leq n$. Moreover, if $d(\lambda, A) \geq 2n + 1$, there exists $\{i, j\} \in E(T)$ and

$\varphi \in \ker(A - \lambda)$ such that, if T_1 and T_2 are the two connected components of T with the edge $\{i, j\}$ deleted, then:

(i) $\varphi(i) = \varphi(j) = 0$

(ii) there exists $a \in V(T_1)$ and $b \in V(T_2)$ such that $\varphi(a) \neq 0$, $\varphi(b) \neq 0$.

Definition 3. Let Z be some submanifold of $\text{Herm}(\mathbb{C}^V)$ or $\text{Sym}(\mathbb{R}^V)$. We recall that an eigenvalue λ of $A \in Z$, where $d(\lambda, A) = l$, is Z -stable if Z and $W_{l,\lambda}$ intersect transversally at A where $W_{l,\lambda}$ is the manifold of all matrices B in $\text{Herm}(\mathbb{C}^V)$ or $\text{Sym}(\mathbb{R}^V)$ such that $\dim \ker(B - \lambda) = l$.

Let us write $d_s(\lambda, A, Z) = d(\lambda, A)$ if $\lambda \in \sigma(A)$ is Z -stable and $d_s(\lambda, A, Z) = 0$ otherwise. Here $Z = M_G \subset \text{Herm}(\mathbb{C}^V)$ or $Z = R_G \subset \text{Sym}(\mathbb{R}^V)$.

It is possible to make the transversality condition more algebraic:

Definition 4. Let $G = (V, E)$ be a graph. If $i \in V$, define $\varepsilon_i(x) = |x_i|^2$ (quadratic form on \mathbb{R}^V or Hermitian form on \mathbb{C}^V) and, if $\{i, j\} \in E$, define

$$\varepsilon_{i,j}(x) = x_i x_j, \quad \{i, j\} \in E$$

(quadratic forms) and

$$\varepsilon'_{i,j}(x) = \Re(x_i \bar{x}_j), \quad \varepsilon''_{i,j}(x) = \Im(x_i \bar{x}_j)$$

(Hermitian forms).

Proposition 2. If $F = \ker(A - \lambda)$, the transversality condition is equivalent to the fact that the space of Hermitian forms (resp. quadratic forms) on F is generated over \mathbb{R} by the restrictions to F of the $|V| + 2|E|$ forms ε_i , $i \in V$

and $\varepsilon'_{i,j}$, $\varepsilon''_{i,j}$, $\{i, j\} \in E$

(resp. of the $|V| + |E|$ forms ε_i , $i \in V$ and $\varepsilon_{i,j}$, $\{i, j\} \in E$).

We have the :

Theorem 2. 1) If $A \in M_G$, $d_s(\lambda_1(A), A, M_G) \leq la(G)$ and,

$$\forall k, d_s(\lambda_k(A), A, M_G) \leq 2la(G);$$

2) if $A \in R_G$, $d_s(\lambda_1(A), A, R_G) \leq la(G)$ and,

$$\forall k, d_s(\lambda_k(A), A, R_G) \leq 2la(G).$$

Of course, these estimates remain valid if $A \in O_G$.

It is possible to reformulate Theorem 2 by introducing the following invariants of graphs :

Definition 5. Let us define

$$\nu_k^{\mathbb{R}}(G) = \max\{d_s(\lambda_k(A), A, R_G) \mid A \in R_G\},$$

$$\nu_k^{\mathbb{C}}(G) = \max\{d_s(\lambda_k(A), A, M_G) \mid A \in M_G\}.$$

Remark : we may have defined $\mu(G)$ by the following equation :

$$\mu(G) = \max\{d_s(\lambda_2, A, O_G) \mid A \in O_G\},$$

and we have :

$$\mu(G) \leq \nu_2^{\mathbb{R}}(G).$$

One of the main results of our paper is the following :

Theorem 3. *The invariants ν_k^K satisfy*

$$\nu_k^K(G') \leq \nu_k^K(G) ,$$

for every minor G' of G .

Remark : One can show that $\nu_2^{\mathbb{R}}(K_{1,3}) = 2$ while $\nu_2^{\mathbb{C}}(K_{1,3}) = 1$.

Is it true in general that :

$$\nu_k^{\mathbb{R}}(G) \geq \nu_k^{\mathbb{C}}(G) ?$$

With definition 5, Theorem 2 becomes :

Theorem 4. *For $K = \mathbb{R}$ or \mathbb{C} , we have:*

$$(i) \nu_1^K(G) \leq la(G) ,$$

$$(ii) \nu_k^K(G) \leq 2 la(G) .$$

In particular, $\mu(G) \leq 2 la(G)$.

As an easy corollary of the previous statements, we have the following characterization of forests which we prove in section 7 :

Theorem 5. *The following conditions are equivalent :*

- (i) G is a forest,
- (ii) $\nu_1^{\mathbb{R}}(G) = 1$,
- (iii) $\nu_1^{\mathbb{C}}(G) = 1$.

It is interesting to observe that the new invariants $\nu_k^K(G)$, which we have introduced above, are not at all related to planarity :

we describe in section 7 a sequence of planar graphs G_n such that

$$\nu_1^{\mathbb{R}}(G_n) = \nu_1^{\mathbb{C}}(G_n) = n ,$$

and

$$la(G_n) = n .$$

Note : *this paper is a complete revision, including new results (in particular, concerning eigenvalues λ_k with $k > 1$) and new proofs, of my preprint [8] .*

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2. A CRUCIAL LEMMA

Lemma 1. *Let $G = (V, E)$ be a finite connected graph and $\{1, 2\} \in E(G)$ such that $G' = (V, E \setminus \{1, 2\})$ is not connected. Let $A \in M_{G,n}$, $F = \ker A$, and let $r : F \rightarrow \mathbb{C}^n \oplus \mathbb{C}^n$ be given by*

$$r(\varphi) = (\varphi(1), \varphi(2)) .$$

Then $\dim r(F) \leq n$.

Proof. The proof is based on Green's formula. Let V_1 be the set of vertices of the connected component of 1 in G' . For any $\varphi, \psi \in F$, let us denote by φ_1, ψ_1 the truncated functions defined by $\varphi_1(i) = \varphi(i)$ if $i \in V_1$ and $\varphi_1(i) = 0$ if $i \notin V_1$; $\psi_1(i) = \psi(i)$ if $i \in V_1$ and $\psi_1(i) = 0$ if $i \notin V_1$.

Let us compute explicitly the righthand side of the following identity:

$$0 = \langle A\varphi_1 | \psi_1 \rangle - \langle \varphi_1 | A\psi_1 \rangle ,$$

using the fact that the only contribution to the scalar products is the value at vertex 1 (if $i \neq 1$, $A\varphi_1(i) = 0$ or $\psi_1(i) = 0$).

Let us compute $A\varphi_1(1)$ using the fact that $A\varphi(1) = 0$; we get

$$A\varphi_1(1) = -A_{1,2}(\varphi(2)) .$$

Hence, the expression to be evaluated reduces to

$$0 = \langle A_{1,2}(\varphi(2)) | \psi(1) \rangle - \langle \varphi(1) | A_{1,2}(\psi(2)) \rangle ,$$

which we call Green's formula.

Let us write $B = A_{1,2}$ and denote by ω the Hermitian form on $\mathbb{C}^n \oplus \mathbb{C}^n$ given by:

$$\omega((x_1, x_2), (y_1, y_2)) = \sqrt{-1}(\langle Bx_2 | y_1 \rangle - \langle x_1 | By_2 \rangle) .$$

It is easy to see that ω is non degenerate, so that any isotropic subspace has dimension at most n ; in particular, this is true for $r(F)$. \square

There exists a modification of the above result which we state without proof:

Lemma 2. *Let $A \in M_G$, $V_1 \subset V$ and let $E_0 = \{e_j = \{a_j, b_j\} \in E, j = 1, \dots, n\}$ the set of all edges $e = \{a, b\}$ of G such that $a \in V_1$ and $b \notin V_1$; let $F = \ker A$, $V_0 = \{a_j, b_j, j = 1, \dots, n\}$ (we have $\#V_0 \leq 2n$).*

If $r : F \rightarrow \mathbb{C}^{V_0}$ is given by the restriction to V_0 , then $\dim r(F) \leq n$.

3. PROOF OF THEOREM 1

Let T be a finite tree with vertices of degree ≤ 3 .

For each edge $\{i, j\} \in E(T)$, let us denote by $\overline{T_{i,j}}$ and $T_{j,i}$ the two subtrees of T obtained by deleting the edge $\{i, j\}$ and such that $i \in V(\overline{T_{i,j}})$ and $j \in V(T_{j,i})$.

Let $n \geq 1$ be some integer and $A \in M_{T,n}$.

Let us write $F = \ker A$. For each $\{i, j\} \in E(T)$, let us denote by $F_{i,j} \subset F$ the vector space of those $\varphi \in F$ which vanish at i and j and whose support lies inside $V(\overline{T_{i,j}})$.

If $r = r_{i,j} : F \rightarrow \mathbb{C}^n \oplus \mathbb{C}^n$ is defined by $r(\varphi) = (\varphi(i), \varphi(j))$ it is easy to check that:

$$\ker r_{i,j} = F_{i,j} \oplus F_{j,i} .$$

We have then the :

Lemma 3. *If $\dim F > n$, there exists $\{i, j\} \in E(T)$ such that*

(i) $F_{i,j}$ is not 0,

(ii) $\text{degree}(i) = 3$,

(iii) the maps $\epsilon_\alpha : F_{i,j} \rightarrow \mathbb{C}^n$ defined by $\phi \rightarrow \phi(\alpha)$, where α is one of the neighbours of i with $\alpha \neq j$, are injective. In particular, $1 \leq \dim F_{i,j} \leq n$.

Corollary 1. *If $\dim F > 2n$, there exists $\{i, j\} \in E(T)$ such that*

$$\dim F_{i,j} \geq 1, \dim F_{j,i} \geq 1 .$$

Corollary 2. *If $A \geq 0$ (i.e. the quadratic form associated to A is positive), $\dim F \leq n$.*

Proof. (Corollary 1)

Choose $\{i, j\}$ according to the lemma and put $F_o = \ker(r_{i,j})$, we have: $\dim F_o \geq n + 1$ (lemma 1), and, because $F_o = F_{i,j} \oplus F_{j,i}$, and $\dim F_{i,j} \leq n$, $F_{j,i}$ is not trivial. \square

Proof. (Corollary 2)

If $\dim F > n$, by (i), there exists $\varphi \in F_{i,j} \setminus 0$, and by (iii) $\varphi(\alpha) \neq 0$, where $\alpha \neq j$ is any neighbor of i . Define ψ by $\psi(k) = \varphi(k)$ for $k \in V(T_{\alpha,i})$ and $\psi(k) = 0$ otherwise. Then $\psi \in \ker A$:

$$(A\psi|\psi) = 0 ,$$

because $A\psi$ vanishes where ψ does not.

Set $Q(f) = (Af|f)$ and let δ be the numerical function on $V(T)$ which is defined by $\delta(i) = 1$ and $\delta(k) = 0$ if $k \neq i$.

Evaluating $Q(\psi + \epsilon\delta v)$ for $v \in \mathbb{C}^n$ and $\epsilon > 0$, we find:

$$Q(\psi + \epsilon\delta v) = 2\epsilon\Re(v|A_{i,\alpha}(\psi(\alpha))) + O(\epsilon^2) .$$

It is always possible to choose v such that

$$Q(\psi + \epsilon\delta v) < 0$$

for $\epsilon > 0$ small enough (because $A_{i,\alpha}$ is non singular and $\psi(\alpha) \neq 0$).

This gives a contradiction with the fact that $A \geq 0$. □

Proof. (Lemma 3)

Choose first arbitrarily some edge $\{i_1, j_1\}$ of T . By lemma 1, we may then assume that F_{i_1, j_1} is not trivial (otherwise permute i_1 and j_1).

It is clear that i_1 is of degree 2 or 3.

If this degree is 2 and if $\{\alpha, j_1\}$ is the set of neighbours of i_1 , $\forall \varphi \in F_{i_1, j_1}$, $\varphi(\alpha) = 0$. We take then $i_2 = \alpha$, $j_2 = i_1$ and iterate.

If this degree is 3 and if $\{j_1, \alpha, \beta\}$ is the set of neighbours of i_1 , then, if the map $\varphi \rightarrow \varphi(\alpha)$ is not injective on F_{i_1, j_1} , one of the spaces F_{α, i_1} or F_{β, i_1} is not trivial; we may assume that the space F_{α, i_1} is not trivial, set $i_2 = \alpha$, $j_2 = i_1$ and iterate.

This process will stop, and yields a solution. □

Reducing to $\lambda_1 = 0$ and $\lambda = 0$, Theorem 1 is an easy reformulation of corollaries 1 and 2.

4. LAGRANGIAN COMPACTIFICATION

4.1. Introduction. We want to stabilize the multiplicities of eigenvalues with respect to minors.

Let us explain what this means.

Consider the graphs $W_n = P_{2n+1} \times K_2$ (P_l is the path with l vertices) and S_n with $V(S_n) = \{1, 2, \dots, 2n+1\}$ and $E(S_n) = \{\{i, i+1\}, \{2j-1, 2j+1\} | i = 1, \dots, 2n, j = 1, \dots, n\}$. For any $A \in M_{W_n}$, $\dim \ker A \leq 2$: if $\varphi \in \ker A$ vanishes at the two vertices in $\{a\} \times V(K_2)$ where a is an end of the path, it is easy to see that φ vanishes identically.

There exists some $A_o \in R_{S_n}$ which is ≥ 0 and $\dim \ker A_o = n+1$. S_n is the union of n triangles and we define the quadratic form q associated with A_o by $q(x) = \sum_t (x_i + x_j + x_k)^2$ where the sum is on the n triangles $t = \{i, j, k\}$ of S_n .

It is easy to check that S_n is a minor of W_n .

In some sense, the small dimension of $\dim \ker A$, for $A \in M_{W_n}$, is not *stable* with respect to minors.

If W is a submanifold of some manifold M and $j : N \rightarrow M$ is a smooth map whose differential is injective, we will say that j is *transversal* to W at $x_o \in N$ if $j(x_o) \in W$ and

$$T_{j(x_o)}M = T_{j(x_o)}W + j'(x_o)(T_{x_o}N).$$

We want to use the basic property of *transversality*, see [12] p. 27 :

if j_ε (ε small real number) is a smooth map from N to M converging to j in the C^1 -topology near x_o to j (it means that j_ε and its first order derivatives converge uniformly to j on some neighbourhood of x_o), then, for ε small enough, there exists $x(\varepsilon) \in N$ such that j_ε is transversal to W at $x(\varepsilon)$.

Let $\lambda_k = 0$ be the k -th eigenvalue having multiplicity l of $A \in M_{G'}$; we can think of this situation as follows : A belongs to the intersection of two submanifolds in $\text{Herm}(\mathbb{C}^{V'})$: the manifold $j(M_{G'})$ (where j is the embedding of $M_{G'}$ into $\text{Herm}(\mathbb{C}^{V'})$) and the manifold W_l of matrices whose kernel has dimension l .

If G' is obtained from G by deleting the edge $\{1, 2\}$, we will denote this by $G' = D_{1,2}(G)$ and we have $V = V'$. We can consider the maps $j_\varepsilon : M_{G'} \rightarrow \text{Herm}(\mathbb{C}^{V'})$ defined by $j_\varepsilon(q) = j(q) + \varepsilon|x_1 - x_2|^2$.

$d_s(0, A_o, M_{G'}) = l$ is equivalent to " j is transversal to W_l at A_o ".

As $j_\varepsilon(M_{G'}) \subset M_G$, the *basic property of transversality* shows that $\nu_k^{\mathbb{C}}(G') \leq \nu_k^{\mathbb{C}}(G)$.

If G' is obtained from G by contracting the edge $\{1, 2\}$ (we shall write $G' = C_{1,2}(G)$), we need to embed $M_{G'}$ and M_G as submanifolds into the same manifold: this is possible using appropriate Grassmann manifolds.

We will now describe the appropriate general tools in order to make stabilization; of course, the same kind of proofs as in [3] applies, but we want to have a more *natural* setting, even if this seems to imply more geometric material !!

4.2. Lagrangian Grassmann manifolds and quadratic forms. In the following, X is a real N -dimensional vector space. In fact, up to obvious changes, everything extends to the complex case.

Proofs will be given only for the real case.

For applications to graphs, X will be \mathbb{R}^V (or \mathbb{C}^V).

Let us denote by Z the space $T^*(X) = X \oplus X^*$, where X^* is the dual of X , endowed with the canonical symplectic form ω defined by

$$\omega((x, \xi), (x', \xi')) = \xi(x') - \xi'(x) .$$

We denote by \mathcal{L}_X (or \mathcal{L} if no ambiguity arises) the Grassmann manifold of the Lagrangian subspaces of Z . Let us recall that a Lagrangian subspace of Z is a maximal subspace which is ω -isotropic: such subspaces are of dimension N and \mathcal{L}_X is a real analytic compact manifold of dimension $N(N+1)/2$, cf Duistermaat [11].

Remark: in the complex case, we need to consider the canonical Hermitian form $\omega_{\mathbb{C}}$ on $X \oplus X^*$, where X^* is the antidual of X , given by

$$\omega_{\mathbb{C}}((x, \xi), (x', \xi')) = \sqrt{-1}(\xi(x') - \bar{\xi}'(x)) ,$$

and the corresponding Grassmann manifold which is of dimension N^2 .

Denote by $\mathcal{Q}(X)$ the vector space of all (real) quadratic forms on X (or all Hermitian forms on X in the complex case).

Every quadratic form $q(x) = (Ax|x)_{X^*, X}$ on X can be identified with the symmetric linear map A from X to X^* and this defines an embedding $J : \mathcal{Q}(X) \rightarrow \mathcal{L}_X$ where $J(q)$ is the graph of the linear map A .

We give the following

Definition 6. $\rho = (q, F)$ will be called a *generalized quadratic form* on X if F is a subspace of X and $q \in \mathcal{Q}(F)$.

To each generalized quadratic form $\rho = (q, F)$, we associate some Lagrangian space:

$$J(\rho) = \{(x, \xi) | x \in F \text{ and } \forall y \in F, C_q(x, y) = \xi(y)\} ,$$

where C_q is the symmetric bilinear form associated with q . In other words, if $B_q : F \rightarrow F^*$ is the linear map associated with q

$$J(\rho) = \{(x, \xi) \in F \times X^* | \xi|_F = B_q x\} .$$

Conversely, if L is a *Lagrangian subspace*, we associate with it a generalized quadratic form $K(L) = \rho = (q, F)$ where F is the projection of L onto X and $\forall x, y \in F, C_q(x, y) = \xi(y)$ where $(x, \xi) \in L$. The fact that $\xi(y)$ is independent of the choice of $(x, \xi) \in L$ comes from the fact that L is a Lagrangian: if (x, ξ) and (x, ξ') are in L , then $(0, \xi - \xi') \in L$ and, for $(y, \eta) \in L$,

$$0 = \omega((0, \xi - \xi'), (y, \eta)) = \xi(y) - \xi'(y) .$$

Using $\omega((x, \xi), (y, \eta)) = 0$, it is clear that C_q is symmetric.

It is easy to check that J and K are inverse maps.

In this way, we have a bijection of \mathcal{L} with the set of all generalized quadratic forms. Since \mathcal{L} is a compact manifold, we have also a compactification of $\mathcal{Q}(X)$. *The corresponding topology on generalized quadratic forms will be called the Lagrangian topology.*

Given a Lagrangian space L_0 , it is possible to identify the tangent space of \mathcal{L} at L_0 with the space $\mathcal{Q}(L_0)$ in the following way: there exist an open dense set in \mathcal{L} of Lagrangian spaces L_1 such that $Z = L_0 \oplus L_1$ and ω identifies L_1 with the dual of L_0 . Lagrangian spaces L which are close enough to L_0 can be considered as graphs of linear maps from L_0 to L_1 and these maps are symmetric once L_1 is identified, using ω , with the dual L_0^* of L_0 .

In this way, we get charts of \mathcal{L} near L_0 .

The following proposition is proved in Duistermaat [11] :

Proposition 3. *All these charts give rise to the same identification of the tangent space at L_0 with $\mathcal{Q}(L_0)$.*

4.3. Some examples of singular limits. We consider a family of symmetric operators from X to X^* of the following type :

$$A(\varepsilon) = A_0 + \frac{1}{\varepsilon}A_1, \varepsilon \neq 0.$$

Proposition 4. *In the manifold \mathcal{L} , the graph of $A(\varepsilon)$ has a limit for $\varepsilon \rightarrow 0$ which is the generalized quadratic form $\Phi(A_0) = (q, F)$ where $F = \ker A_1$ and q is the restriction to F of the quadratic form associated with A_0 .*

Moreover the maps Φ_ε from $\text{Sym}(X)$ to \mathcal{L} defined by $\Phi_\varepsilon(A_0) = J(A_0 + \frac{A_1}{\varepsilon})$ converge in the C^1 topology to Φ .

Proof. Let us consider the decompositions $X = U \oplus V$, with $U = \ker A_1$ and $A_1(V) \subset V^*$, and $X^* = U^* \oplus V^*$. We describe then the graph of $A(\varepsilon)$ in the following way. For $u \in U$, $v \in V$, let us write $A(\varepsilon)(u, v) = (\xi, \eta)$ with $\xi \in U^*$ and $\eta \in V^*$, then we have :

$$\xi = B(u, v), \quad \eta = C(u) + D(v) + \frac{1}{\varepsilon}Gv,$$

(here $B : X \rightarrow U^*$, $C : U \rightarrow V^*$, D and $G : V \rightarrow V^*$ are linear maps and G is non-singular) which may be rewritten as

$$\xi = B(u, v), \quad (G + \varepsilon D)(v) = \varepsilon(\eta - C(u)).$$

For ε small, $G + \varepsilon D$ is close to G and hence invertible ; from the second equation, we obtain, for ε small enough :

$$v = \varepsilon K(\varepsilon)(\eta, u),$$

where $K(\varepsilon) : V^* \oplus U \rightarrow V$ is linear, and inserting into the first one :

$$\xi = L(\varepsilon)(\eta, u),$$

where $L(\varepsilon) : V^* \oplus U \rightarrow U^*$ is linear. This shows that the graphs L_ε of $A(\varepsilon)$ admit a limit L_0 as ε goes to 0 which is the graph of the map

$$(\eta, u) \rightarrow (v = 0, \xi = B(u, 0))$$

from $V^* \oplus U$ into $V \oplus U^*$.

It remains to check that $K(L_o)$ is the *generalized quadratic form* $\rho = (q, U)$ where q is the restriction to U of the quadratic form associated with A_o . This comes from the definition of B .

The C^1 convergence of Φ_ε to Φ comes from the fact that $D \rightarrow (G + \varepsilon D)^{-1}$ is C^1 . □

More generally, we can prove the following result:

Proposition 5. *Any meromorphic map from some open set $\Omega \subset \mathbb{C}$ into $\text{Sym}(X)$ extends to a holomorphic map into \mathcal{L}_X .*

4.4. Stratification of the Lagrangian Grassmann manifold. Fix some Lagrangian space $K_0 \in \mathcal{L}$ and denote by W_l the set of all Lagrangian spaces L such that $\dim(L \cap K_0) = l$.

If $Z = X \oplus X^*$, $K_0 = X \oplus 0$ and if $\rho = (q, F)$ is a generalized quadratic form, it is equivalent to say that $J(\rho) \in W_l$ and that $\dim \ker q = l$. this definition of W_l is the natural extension to the generalized quadratic forms of the definition of $W_{l,0}$ given in definition 3.

The following theorem is proved in Duistermaat [11] :

Theorem 6. *W_l is a (non closed) submanifold of \mathcal{L} whose tangent space at L is the set of quadratic forms on L which vanish identically on $L \cap L_0$.*

Comments: this result is strongly related to the perturbation theory of degenerate eigenvalues. If $Z = X \oplus X^*$ and $L_0 = X \oplus 0$, for any $A \in \text{Sym}(X)$ whose graph is L_A , we have :

$$\dim \ker A = \dim(L_0 \cap L_A) .$$

Moreover, if this dimension is ≥ 1 , eigenvalues close to 0 of $A_\varepsilon = A + \varepsilon B$ are very close to eigenvalues of the quadratic form associated to B restricted to $\ker A$.

5. MONOTONY FOR MINORS

In this section, we will show how to stabilize bounds on multiplicities with respect to minors, using the previous tools (transversality, Lagrangian Grassmann manifolds).

5.1. **Minors.** We will say that G' is a minor of G if G' is obtained from G by a sequence of the following three operations :

- (D) which consists in deleting one edge.
- (C) which consists in contracting one edge and identifying its two end vertices.
- (R) which consists in deleting one isolated vertex.

It is possible to describe this in a more global way :

let us give a partition $V = \cup_{\alpha \in W} V_{\alpha}$ of the vertex set of G into connected subsets. $V(G')$ is a subset of W , and $E' = E(G')$ satisfies :

$$(\{\alpha, \beta\} \in E') \Rightarrow (\exists i \in V_{\alpha}, j \in V_{\beta}, \{i, j\} \in E) .$$

If we study some property (P) of graphs which is hereditary with respect to minors (for instance, the existence of an embedding in a given surface), a deep and difficult result (Wagner's conjecture, proved by Robertson and Seymour in a series of papers in JCTB) states that this property is characterized by a *finite* number of excluded minors : there exists a *finite* list of graphs such that (P) is equivalent to the property of *having no minor in this list*.

The simplest example is the characterization of forests by excluding the triangles as a minor.

Some further classical example is Kuratowski's characterization of planar graphs by excluding K_5 and $K_{3,3}$ as minors.

5.2. **Monotony.** We will now prove Theorem 3.

Proof.

We will give the proof in the real case (i.e. $K = \mathbb{R}$).

It is enough to show the result for $G' = D_{1,2}(G)$ or $G' = C_{1,2}(G)$ where $\{1, 2\}$ is some edge of G . The most difficult case is the contraction of an edge since then $\mathbb{R}^{V'}$ is not equal to \mathbb{R}^V . We will only give the proof for this case.

Let us denote by 0 the vertex of G' which is obtained by contracting the edge $\{1, 2\} \in E(G)$, by B the set of vertices of G which are adjacent to 1, but not to 2, by C the set of vertices which are adjacent to 2, but not to 1, and by D the set of vertices which are adjacent to 1 and 2.

We will define maps j_ε , $\varepsilon > 0$, from $R_{G'}$ to $R_G \subset \text{Sym}(\mathbb{R}^V) \subset \mathcal{L}_V$. Let us denote by k_0 the embedding of $\text{Sym}(\mathbb{R}^{V'})$ into \mathcal{L}_V , which associates to the quadratic form q on $\mathbb{R}^{V'}$, the Lagrangian space $J(\rho)$ where $\rho = (Q, D_{1,2})$ on \mathbb{R}^V is defined in the following way : its domain $D_{1,2}$ is the subspace defined by the equation $\{x_1 = x_2\}$ and Q is defined by transferring q to $D_{1,2}$, using the bijection $\varphi : \mathbb{R}^{V'} \rightarrow D_{1,2}$ defined by : $\varphi(x_0, x_3, \dots, x_N) = (x_0, x_0, x_3, \dots, x_N)$. We will then prove, using proposition 4, that j_ε converges in the C^1 topology to j_0 , the restriction of k_0 to $R_{G'}$.

Let $q(x_0, x_3, \dots, x_N)$ be some quadratic form in $R_{G'}$, we associate to it $j_\varepsilon(q) = J(q_\varepsilon)$ in the following way :

let us write

$$q(x_0, x_3, \dots, x_N) = W_0 x_0^2 + \sum_{j \sim 0} c_{0,j} (x_j - x_0)^2 + r(x_3, \dots, x_N) .$$

We define :

$$\begin{aligned} q_\varepsilon(x_1, \dots, x_N) &= \frac{1}{\varepsilon} (x_1 - x_2)^2 + W_0 x_1^2 + \sum_{j \in B} c_{0,j} (x_1 - x_j)^2 + \sum_{j \in C} c_{0,j} (x_2 - x_j)^2 \\ &+ \sum_{j \in D} \frac{c_{0,j}}{2} ((x_1 - x_j)^2 + (x_2 - x_j)^2) + r(x_3, \dots, x_N) . \end{aligned}$$

With this definition, $q_\varepsilon \in R_G$ and the restriction of q_ε to $D_{1,2}$ is the same as $q(x_1, x_3, \dots, x_N)$.

Using proposition 4, we see that j_ε converges smoothly to j_0 .

Let us denote by $W'_l \subset \text{Sym}(\mathbb{R}^{V'})$ the set of matrices whose kernel is of dimension l . If $d_s(0, A_0, R_{G'}) = l$, by definition

$$\text{Sym}(\mathbb{R}^{V'}) = T_{A_0} W'_l + T_{A_0} R_{G'} .$$

If $Z = k_0(\text{Sym}(\mathbb{R}^{V'}))$ and $Y = j_0(R_{G'})$, and using the fact that $k_0(W'_l) = W_l \cap Z$, we observe that, writing $L_0 = j_0(A_0)$, $T_{L_0} Z = T_{L_0} Y + T_{L_0}(W_l \cap Z)$.

We have then the :

Lemma 4. *Using the same notations as before, $j_0 : R_{G'} \rightarrow \mathcal{L}_V$ is transversal to W_l at A_0 : absolute and relative transversality are identical.*

Proof. We begin with the following observation:

$$T_{L_0}(\mathcal{L}_V) = T_{L_0} W_l + T_{L_0} Z .$$

Indeed, using proposition 3 and theorem 6 and writing $H = L_0 \cap (\mathbb{R}^V \oplus 0) = \ker A_0$, we have : $T_{L_0}(\mathcal{L}_V) = \mathcal{Q}(L_0)$, $T_{L_0} W_l = \{q \in \mathcal{Q}(L_0) | q|_H = 0\}$ and $T_{L_0}(Z) = \{S \circ \pi\}$

where π is the projection from L_0 to $D_{1,2}$ and $S \in \mathcal{Q}(D_{1,2})$. The observation follows then from the fact that $H \subset D_{1,2}$.

We use now the fact that

$$T_{L_0}(Z) = T_{L_0}(W_l \cap Z) + j'_0(T_{A_0}(R_{G'})) ,$$

to conclude that :

$$T_{L_0}(\mathcal{L}_V) = T_{L_0}(W_l) + j'_0(T_{A_0}(R_{G'})) .$$

□

Let q_0 be the quadratic form associated with $A_0 \in R_{G'}$ such that $\lambda_k(A_0) = 0$ and

$$d_s(0, A_0, R_{G'}) = l .$$

We have seen that j_ε converges smoothly to j_0 . By the basic property of transversality, for $\varepsilon > 0$ small enough, there exists some $A_\varepsilon \in j_\varepsilon(R_{G'})$ such that $\lambda_k(A_\varepsilon) = 0$ and $d_s(0, A_\varepsilon, j_\varepsilon(R_{G'})) = l$. Then, because $j_\varepsilon(R_{G'}) \subset R_G$, $d_s(0, A_\varepsilon, R_G) = l$.

This completes the proof of theorem 3.

5.3. Proof of Theorem 2. First, define the product $K = G \times H$ of two graphs G and H by:

$$V(K) = V(G) \times V(H) ,$$

and

$$\{(g_1, h_1), (g_2, h_2)\} \in E(K) \text{ if and only if } g_1 = g_2 \text{ and } \{h_1, h_2\} \in E(H)$$

$$\text{or } h_1 = h_2 \text{ and } \{g_1, g_2\} \in E(G) .$$

Let us now prove the second part of Theorem 2 (i.e. the real case):

Proof. Let G be a graph such that $la(G) = n$; then, there exists some tree T with vertices of degree ≤ 3 such that G is a minor of $T \times K_n$. Hence

$$\nu_k^{\mathbb{R}}(G) \leq \nu_k^{\mathbb{R}}(T \times K_n) .$$

We will use the natural identification of $\mathbb{C}^{V(T \times K_n)}$ with the space of maps from $V(T)$ into \mathbb{C}^n .

Using this identification, every scalar elliptic self-adjoint operator A on $T \times K_n$ becomes an elliptic self-adjoint n -differential operator on T .

$k=l$: in this case, by Theorem 1, the multiplicity of the ground state of $T \times K_n$ is always $\leq n$.

k arbitrary: if $\nu_k^{\mathbb{R}}(T \times K_n) > 2n$, there exists $A \in R_{T \times K_n}$ such that $d_s(\lambda_k, A, R_{T \times K_n}) > 2n$. Applying Theorem 1 (and using the notations there), let us denote by φ_i , $i = 1, 2$ the restrictions of φ to $V(T_i)$ extended by 0 outside T_i . Then $\varphi_i \in \ker(A - \lambda_k)$, for any $\alpha \in V(T \times K_n)$, $\varepsilon_\alpha(\varphi_1, \varphi_2) = 0$ (we identify here ε_α with the associated bilinear form) because supports are disjoint, and for any $\{\alpha, \beta\} \in E(T \times K_n)$, $\varepsilon_{\alpha, \beta}(\varphi_1, \varphi_2) = 0$, because there is no edge $\{\alpha, \beta\}$ for which $\varphi_1(\alpha)\varphi_2(\beta) \neq 0$.

This shows that transversality does not hold.

□

6. TREE-WIDTHS

In [18], N. Robertson and P. Seymour give the following definition for the *tree-width* $tw(G)$ of a graph G : we define a *tree-like decomposition* of G as a pair (T, \mathcal{X}) where T is a tree and where $\mathcal{X} = \{X_t | t \in V(T)\}$ is a family of subsets of $V(G)$ indexed by $t \in V(T)$, such that the following conditions hold :

$$(6.1) \quad V(G) = \cup_{t \in V(T)} X_t$$

$$(6.2) \quad \forall e = \{a, b\} \in E(G), \exists t \text{ such that } a, b \in X_t$$

$$(6.3) \quad \forall x, y \in V(T), \forall z \in]x, y[, X_x \cap X_y \subset X_z$$

Here $]x, y[$ denotes the set of interior vertices of the unique path between x and y .

We define then the width of (T, \mathcal{X}) by :

$$w(T, \mathcal{X}) = \max |X_t| - 1 ,$$

and

$$tw(G) = \min w(T, \mathcal{X})$$

where the min is among all tree-like decompositions of G .

On the other hand, we define some closely related invariant $la(G)$ as follows.

We define $la(G)$ as the minimum N such that G is a minor of some product $T \times K_N$ where T is a tree and K_N is the clique with N vertices.

We want to prove proposition 1.

Remark: in [14] p. 91, Hein van der Holst proves a sharper inequality:

$$tw(G) \leq la(G) .$$

Proof. ($tw(G) \leq 2la(G) - 1$)

By definition, there exists a tree T such that G is a minor of $T \times K_N$ where $N = la(G)$. Since tw is monotonous with respect to the minor relation we have $tw(G) \leq tw(T \times K_N)$ and it is hence enough to prove the inequality $tw(T \times K_N) \leq 2N - 1$.

We will construct a tree-like decomposition (T, \mathcal{X}) of $T \times K_N$: orient first T from some choosen root α and write $X_t = \{t_-, t\} \times V(K_N)$ where t_- is the unique predecessor of t (for $t \neq \alpha$) and $X_\alpha = \{\alpha\} \times V(K_N)$.

It is clear that we get in this way a tree-like decomposition of $T \times K_N$ whose width is $2N - 1$. \square

Proof. ($la(G) \leq tw(G) + 1$.)

Let (T, \mathcal{X}) , $\mathcal{X} = \{X_t | t \in T\}$, with $tw(G) = w(T, \mathcal{X}) = N - 1$, be a tree-like decomposition of G .

Let G' be the graph whose vertices are the pairs (t, x) with $t \in V(T)$, $x \in X_t$, and whose edges are of the form $\{(t, x), (t, x')\}$ with $\{x, x'\} \in E$ and of the form $\{(t, x), (t', x)\}$ where $\{t, t'\}$ is an edge of T and $x \in X_t \cap X_{t'}$.

Then G is a minor of G' : contract the edges of the form $\{(t, x), (t', x)\}$ and use the fact that $A_x = \{t | x \in X_t\}$ induces a connected subgraph of T (a reformulation of property (6.3) of a tree-like decomposition) to embed the resulting vertex set in $V(G)$. This vertex set is actually $V(G)$ by (6.1) and all edges of G are present by (6.2).

And G' is a minor of $T \times K_N$: to see this, it is enough to construct some injective map

$$j : V(G') \rightarrow V(T) \times \{1, \dots, N\}$$

which satisfies

1) $j(t, x) = (t, n(t, x))$

2) for any $x \in X_t \cap X_{t'}$, $n(t, x) = n(t', x)$.

We construct j starting from some root α of T : we choose an arbitrary numbering of X_α and propagate it along the edges of T using the condition 2).

□

7. THE GRAPHS G_n

Here, we will give an explicit family of planar graphs $G_n = (V_n, E_n)$ such that :

(i) $\nu_1^K(G_n) = n$ for $K = \mathbb{R}$ and for $K = \mathbb{C}$,

(ii) $la(G_n) = n$.

Remark : I do not know a proof of $la(G_n) \geq n$ not using spectral methods !!

G_n can be considered as the 1-skeleton of the regular subdivision of an equilateral triangle into $(n-1)^2$ small equilateral triangles. Each edge of the big triangle is divided into $n-1$ edges belonging to some small triangles. We may describe vertices of G_n by their Cartesian coordinates in the basis (e, f) of $\mathbb{R}^2 = \mathbb{C}$ ($e = (1, 0)$, $f = (\frac{1}{2}, \frac{\sqrt{3}}{2})$) :

$$V_n = \{S_{m,k} = me + kf | 0 \leq m \leq n-1, 0 \leq k \leq n-1, m+k \leq n-1\} .$$

It is easy to check that G_n is a minor of $P_{3n} \times P_n$, where P_k is the path with k vertices ; this shows that $la(G_n) \leq n$. We will prove that $\nu_1^{\mathbb{C}}(G_n) = n$; the same kind of proof works for $K = \mathbb{R}$. By Theorem 4, it shows that $la(G_n) \geq n$.

First, for any $A \in M_{G_n}$, $\dim(\ker(A)) \leq n$: otherwise there exists a nonzero function in $\ker(A)$ which vanishes on the n vertices $S_{0,0}, S_{1,0}, \dots, S_{n-1,0}$. It is clear that such a function φ vanishes identically because we can compute (using $A\varphi = 0$) by induction on k its values on the vertices $S_{.,k}$ from its values on the vertices $S_{.,k'}, k' < k$.

For the converse, we exhibit an element $A \in M_{G_n}$. The most simple one has real coefficients :

$$A\varphi(z) = \sum_{z' \sim z} \varphi(z') + \frac{d(z)}{2} \varphi(z) ,$$

where $d(z)$ is the degree of z ($d(z) = 2, 4$ or 6 depending on the position of z). It is easier to define A by his quadratic form $q_A(x) = \langle Ax | x \rangle$.

Call a triangle of G_n *black* if it is of the form $(z, z+e, z+f)$. Then we have :

$$q_A(x) = \sum_{T=\{i,j,k\}} (x_i + x_j + x_k)^2 ,$$

where the summation is on all black triangles T .

It is easy to check the following facts :

(i) $A \in R_{G_n}$ because each edge of G_n is (in a unique way) an edge of some black triangle,

(ii) A is non negative,

(iii) the dimension of the kernel F of A is n because q_A is written as a sum of $|V(G_n)| - n$ (number of black triangles) squares of independent linear forms.

More precisely, there exists functions

$$\varphi_l \quad (l = 0, \dots, n-1)$$

where $\varphi_l(S_{i,0}) = \delta_{i,l}$ which form a basis of F .

What remains to be done is to check transversality.

Proof. We need first the

Lemma 5. *The support of φ_l consists of the $S_{m,k}$ in V_n which satisfy:*

$$l - k \leq m \leq l .$$

The lemma follows from the relations :

$$\varphi_l(S_{m,k}) = -(\varphi_l(S_{m,k-1}) + \varphi_l(S_{m+1,k-1}))$$

which are very close to the relations between binomial coefficients and can be solved explicitly :

$$\varphi_l(S_{m,k}) = (-1)^k C_k^{m+k-l} .$$

We will use proposition 2.

Let us introduce some notations. F is identified with $\mathbb{C}^{\{0,1,\dots,n-1\}}$ using the basis φ_l . We denote by $H = \text{Herm}(F)$ the set of Hermitian forms on F and introduce a filtration

$$H_0 \subset H_1 \subset \dots \subset H_{n-1} = H$$

in the following way : H_l is the set of Hermitian matrices whose entries $h_{i,j}$ vanish for $|i-j| > l$.

We introduce the space $Q \subset \text{Herm}(\mathbb{C}^{V_n})$ which is generated by the n^2 independent forms (using the notations of definition 4) :

$$\begin{aligned} \varepsilon_{m,0} &= \varepsilon_{S_{m,0}}, \quad m = 0, \dots, n-1, \\ \varepsilon'_{m,k} &= \varepsilon'_{z,z-f}, \quad \varepsilon''_{m,k} = \varepsilon''_{z,z-f}, \end{aligned}$$

for $z = S_{m,k}$, $k \geq 1$.

We introduce the filtration $Q_0 \subset \dots \subset Q_{n-1} = Q$ where Q_0 is generated by the $\varepsilon_{m,0}$, and Q_l , for $l \geq 1$, is generated by Q_0 and the $\varepsilon'_{m,k}$ and $\varepsilon''_{m,k}$ with $k \leq l$.

It is enough to prove that, if $\rho : Q \rightarrow H$ is the restriction to F , ρ is an isomorphism.

In fact, ρ is compatible with the filtrations :

$$\rho(Q_l) \subset H_l .$$

For example, we have:

$$\rho(\varepsilon'_{m,k})(\varphi_i, \varphi_j) = \frac{1}{2}(\varphi_i(S_{m,k})\varphi_j(S_{m,k-1}) + \varphi_i(S_{m,k-1})\varphi_j(S_{m,k})) ,$$

which vanishes if $|i-j| > k$ by Lemma 5.

We shall check that :

$$\rho_l : \frac{Q_l}{Q_{l-1}} \rightarrow \frac{H_l}{H_{l-1}}$$

is an isomorphism for $l \geq 0$ (setting $Q_{-1} = H_{-1} = 0$).

Both spaces have the same dimension (n if $l = 0$ and $2(n - l)$ if $l \geq 1$).

Let us compute

$$B = \rho(\epsilon'_{m,k})(\sum x_i \varphi_i, \sum x_i \varphi_i) ;$$

we find:

$$B = \Re(\sum x_i \bar{x}_j \varphi_i(S_{m,k}) \varphi_j(S_{m,k-1})) ,$$

and the product $\varphi_i(S_{m,k}) \varphi_j(S_{m,k-1})$ vanishes if $|i - j| > k$ and, if $|i - j| = k$, it vanishes too unless $j = m$, $i = m + k$. This shows that ρ_l ($l > 0$) has a diagonal non-singular matrix with respect to the basis

$$\epsilon'_{m,l}, \epsilon''_{m,l}$$

for Q_l/Q_{l-1} and the basis of H_l/H_{l-1} consisting of elementary Hermitian matrices with nonzero entries at places where $|i - j| = l$. □

Remark : we started with a (slightly) more complicated example which is gauge equivalent to this one.

Let us define a *holomorphic function* on $V(G_n)$ by the condition that the image of any direct black triangle has to be a direct equilateral triangle.

Define $B \in M_{G_n}$ by the associated Hermitian form

$$q_B(\varphi) = \sum_z |\varphi(z + f) - \varphi(z) - e^{i\pi/3}(\varphi(z + e) - \varphi(z))|^2 ,$$

where the summation is on the $z = S_{m,k}$ with $m + k < n - 1$. Then the kernel of B is the space of holomorphic functions on G_n and B is unitarily equivalent to A by the gauge transformation :

$$\varphi(S_{m,k}) = e^{(2m+k)\frac{2i\pi}{3}} \varphi_1(S_{m,k}) ,$$

i.e. $q_B(\varphi) = q_A(\varphi_1)$.

It remains to prove Theorem 5. In one direction, it follows from Theorem 2. In the other one, it follows from the fact $\nu_1^K(G_2) = 2$ and from the characterization of forests as graphes whose G_2 is not a minor.

8. QUESTIONS

Here is a selection of open questions which were presented at a CWI seminar.

1. Computability questions

Find algorithms computing $\mu(G)$ and $\nu_k^K(G)$ for a given graph G . Theoretically, there exist algorithms because everything can be expressed in terms of intersections of algebraic manifolds. Of course, it would be nice to have a computer program which computes these numbers.

2. Maximizing the gap

Let us come back to the real case. For many purposes it is interesting to have matrices A in O_Γ with a large gap ($\text{gap}(A) = \lambda_2 - \lambda_1$). The problem is to find an appropriate normalization condition which insures that the problem is well posed. Moreover, it seems reasonable to think that the multiplicity of $\lambda_2(A)$ is the largest possible if A maximizes the gap. Compare with [17] for the continuous case.

3. $\nu_k^K(G)$ and $tw(G)$

From general results by Robertson and Seymour, there exist functions $F_k^K : \mathbb{N} \rightarrow \mathbb{N}$ such that

$$tw(G) \leq F_k^K(\nu_k^K(G))$$

holds for planar graphs G . The question is to find some explicit functions $F_k^K : \mathbb{N} \rightarrow \mathbb{N}$, in other words to find explicit upper bounds for $tw(G)$ in terms of $\nu_k^K(G)$.

4. Higher dimensional complexes

The question is to extend the invariants considered in this paper to higher dimensional complexes, and find the relationship with Hodge-de Rham Laplace operators on forms.

5. Chromatic number

This problem is the most exciting: prove or disprove

$$\chi(G) \leq \mu(G) + 1 ,$$

where $\chi(G)$ is the chromatic number of G . This would imply the 4-color theorem and is weaker than the Hadwiger conjecture.

6. Prescribing spectras

Describe all possible spectra for $A \in O_G$ or $A \in R_G$ or $A \in M_G$. Already for special graphs like trees this problem is not yet solved. It is solved for paths and for cycles.

For the cycle on N vertices C_N , we have the following set of inequalities for any $A \in O_{C_N}$:

$$\lambda_1 < \lambda_2 \leq \lambda_3 < \lambda_4 \leq \lambda_5 < \dots .$$

It is known that for any graph G with N vertices and any subset $\sigma = \{\lambda_1 < \lambda_2 < \dots < \lambda_N\}$ of \mathbb{R} , there exists $A \in O_G$ such that

$$\text{Spectrum}(A) = \sigma .$$

There is a general question: is it always true that the restrictions on possible spectra are given by restrictions on the multiplicities of eigenvalues? More precisely, if there exists $A_o \in O_G$ whose spectrum is $\{\lambda_1 < \lambda_2 < \dots < \lambda_N\}$ with multiplicity(λ_i) = n_i , $1 \leq i \leq N$, does there exists for any given $\mu_1 < \dots < \mu_N$ some $A \in O_G$ whose spectrum is $\{\mu_1 < \dots < \mu_N\}$ with multiplicity(μ_i) = n_i , $1 \leq i \leq N$?

7. Lex Schrijver's question

Is it always true that

$$\mu(G) = \min_{G \text{ minor of } G'} m(G') ,$$

where $m(G')$ is the maximal multiplicity of the second eigenvalue for $A \in O_{G'}$?

This is true for example for planar graphs because $\mu(G) \leq 3$ if G is planar and we can use the characterisations given in [3] of graphs with $\mu(G) = 1, 2, 3$.

Same question for $\nu_k^K(G)$.

8. Bounds on multiplicities using fluxes

Given some $A \in M_G$, we may define the flux of the magnetic field through each cycle of G as a number in $\mathbb{R}/2\pi\mathbb{Z}$: if $\gamma = (a_1, a_2, a_N)$ with $\forall i (1 \leq i \leq N)$, $\{a_i, a_{i+1}\} \in E(G)$ ($a_{N+1} = a_1$), the flux of the magnetic field associated with A is the argument of the product $\prod_{i=1}^N A_{i, i+1}$.

Question: is there any upper bound of $\dim(\ker A)$ for $A \in M_G$ in terms of information on the flux?

For this problem, it is interesting to compare with the paper of Lieb and Loss [15].

9. Critical graphs

Find critical graphs for $\mu(G)$ and $\nu_k^K(G)$; G is *critical* for ν if every strict minor G' of G satisfies $\nu(G') < \nu(G)$.

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