

Entropy and Zeta Functions for One-dimensional Multi-layer Cellular Neural Networks

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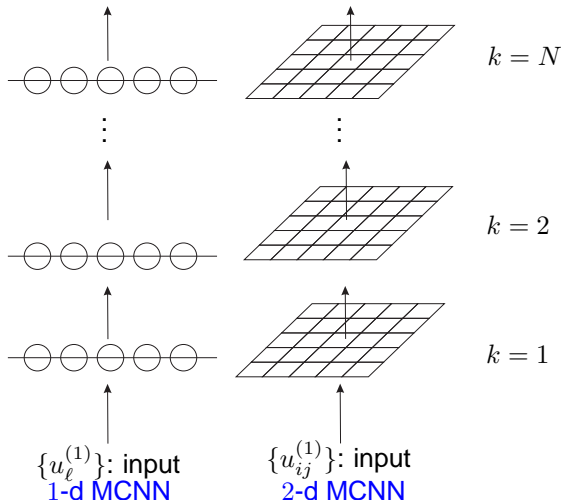
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- L.O. Chua and L. Yang



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$$(1) \left\{ \begin{array}{l} \frac{dx_i^{(1)}}{dt} = -x_i^{(1)} + \sum_{|k| \leq d} a_k^{(1)} y_{i+k}^{(1)} + \sum_{|k| \leq d} b_k^{(1)} u_{i+k}^{(1)} + z^{(1)}, \\ \frac{dx_i^{(2)}}{dt} = -x_i^{(2)} + \sum_{|k| \leq d} a_k^{(2)} y_{i+k}^{(2)} + \sum_{|k| \leq d} b_k^{(2)} u_{i+k}^{(2)} + z^{(2)}, \\ \vdots \\ \frac{dx_i^{(N)}}{dt} = -x_i^{(N)} + \sum_{|k| \leq d} a_k^{(N)} y_{i+k}^{(N)} + \sum_{|k| \leq d} b_k^{(N)} u_{i+k}^{(N)} + z^{(N)}, \end{array} \right.$$

where

$$y_i^{(k)} = u_i^{(k+1)}, \quad 1 \leq k \leq N-1$$

and

$\{u_i^{(1)}\}$: input data.

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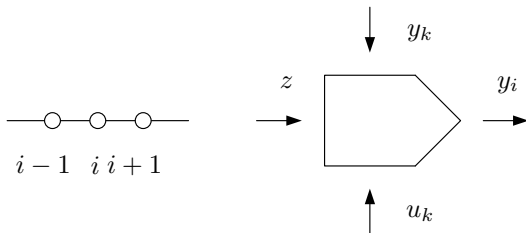
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Consider $N = 1$ and $d = 1$,

$$\frac{dx_i}{dt} = -x_i + a_l y_{i-1} + a y_i + a_r y_{i+1} + b_l u_{i-1} + b u_i + b_r u_{i+1} + z.$$

The diagram of this CNN model:



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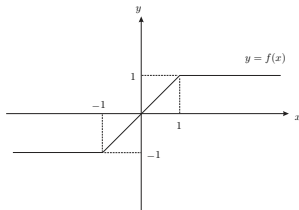
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● Output function

$$y = f(x) = \frac{1}{2}(|x + 1| - |x - 1|).$$



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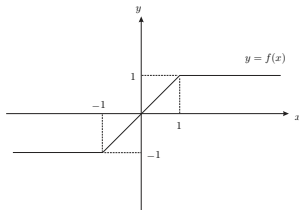
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● Output function

$$y = f(x) = \frac{1}{2}(|x + 1| - |x - 1|).$$



● Initial conditions

$$u_i^{(k)}(0) = u_i^{(k)} \text{ and } x_i^{(k)}(0) : \text{constant}$$

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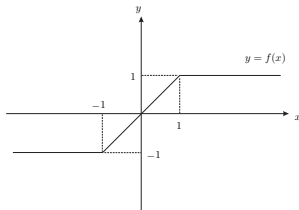
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● Output function

$$y = f(x) = \frac{1}{2}(|x + 1| - |x - 1|).$$



● Initial conditions

$$u_i^{(k)}(0) = u_i^{(k)} \text{ and } x_i^{(k)}(0) : \text{constant}$$

● Parameters

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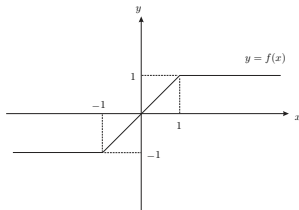
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● Output function

$$y = f(x) = \frac{1}{2}(|x + 1| - |x - 1|).$$



● Initial conditions

$$u_i^{(k)}(0) = u_i^{(k)} \text{ and } x_i^{(k)}(0) : \text{constant}$$

● Parameters

- $A^{(k)}$: feedback template.

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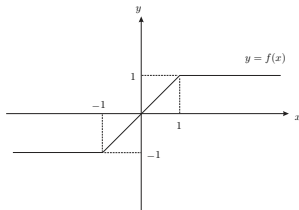
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- Output function

$$y = f(x) = \frac{1}{2}(|x + 1| - |x - 1|).$$



- Initial conditions

$$u_i^{(k)}(0) = u_i^{(k)} \text{ and } x_i^{(k)}(0) : \text{constant}$$

- Parameters

- $A^{(k)}$: feedback template.
- $B^{(k)}$: controlling template.

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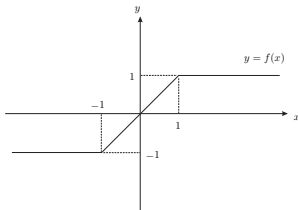
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● Output function

$$y = f(x) = \frac{1}{2}(|x + 1| - |x - 1|).$$



● Initial conditions

$$u_i^{(k)}(0) = u_i^{(k)} \text{ and } x_i^{(k)}(0) : \text{constant}$$

● Parameters

- $A^{(k)}$: feedback template.
- $B^{(k)}$: controlling template.
- $z^{(k)}$: threshold.

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Definition 1.1

• Mosaic patterns (Output patterns)

$$\left\{ (y_i^{(k)}) \right\}_{\substack{i \in \mathbb{Z} \\ 1 \leq k \leq N}} \iff |y_i^{(k)}| = 1$$

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Definition 1.1

● Mosaic patterns (Output patterns)

$$\{(y_i^{(k)})\}_{\substack{i \in \mathbb{Z} \\ 1 \leq k \leq N}} \iff |y_i^{(k)}| = 1$$

● Mosaic input $\{(u_i^{(1)})\} \iff |u_i^{(1)}| = 1, i \in \mathbb{Z}.$

Consider $A^{(k)} = (a_l^{(k)}, a^{(k)}, a_r^{(k)})$, $B^{(k)} = (b_l^{(k)}, b^{(k)}, b_r^{(k)})$

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Consider $A^{(k)} = (a_l^{(k)}, a^{(k)}, a_r^{(k)})$, $B^{(k)} = (b_l^{(k)}, b^{(k)}, b_r^{(k)})$

Parameters space $\{(A^{(1)}, B^{(1)}, z^{(1)}), \dots, (A^{(N)}, B^{(N)}, z^{(N)})\}$

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Consider $A^{(k)} = (a_l^{(k)}, a^{(k)}, a_r^{(k)})$, $B^{(k)} = (b_l^{(k)}, b^{(k)}, b_r^{(k)})$

Parameters space $\{(A^{(1)}, B^{(1)}, z^{(1)}), \dots, (A^{(N)}, B^{(N)}, z^{(N)})\}$

In (1), consider stationary solutions:

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Consider $A^{(k)} = (a_l^{(k)}, a^{(k)}, a_r^{(k)})$, $B^{(k)} = (b_l^{(k)}, b^{(k)}, b_r^{(k)})$

Parameters space $\{(A^{(1)}, B^{(1)}, z^{(1)}), \dots, (A^{(N)}, B^{(N)}, z^{(N)})\}$

In (1), consider stationary solutions:

MCNN $\implies N$ -coupled map lattice

$$(2) \left\{ \begin{array}{l} x_i^{(1)} = a_l^{(1)} y_{i-1}^{(1)} + a^{(1)} y_i^{(1)} + a_r^{(1)} y_{i+1}^{(1)} \\ \quad + b_l^{(1)} u_{i-1}^{(1)} + b^{(1)} u_i^{(1)} + b_r^{(1)} u_{i+1}^{(1)} + z^{(1)}, \\ x_i^{(2)} = a_l^{(2)} y_{i-1}^{(2)} + a^{(2)} y_i^{(2)} + a_r^{(2)} y_{i+1}^{(2)} \\ \quad + b_l^{(2)} y_{i-1}^{(1)} + b^{(2)} y_i^{(1)} + b_r^{(2)} y_{i+1}^{(1)} + z^{(2)}, \\ \quad \vdots \\ x_i^{(N)} = a_l^{(N)} y_{i-1}^{(N)} + a^{(N)} y_i^{(N)} + a_r^{(N)} y_{i+1}^{(N)} \\ \quad + b_l^{(N)} y_{i-1}^{(N-1)} + b^{(N)} y_i^{(N-1)} + b_r^{(N)} y_{i+1}^{(N-1)} + z^{(N)}. \end{array} \right.$$

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Question

$$(I) \{ \text{input } (u_i^{(1)}) \} \equiv \mathcal{I} \longrightarrow \{ \text{outputs } (y_i^{(N)}) \} \equiv \mathcal{Y}$$

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Question

(I) $\{ \text{input } (u_i^{(1)}) \} \equiv \mathcal{I} \longrightarrow \{ \text{outputs } (y_i^{(N)}) \} \equiv \mathcal{Y}$

- (II) Complexity of $\{ \text{outputs} \} \equiv \mathcal{Y}$.
- (i) Spatial entropy.
 - (ii) Zeta function.

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In (1), consider $N = 1$ and $d = 1$.

$$(3) \frac{dx_i}{dt} = -x_i + a_l y_{i-1} + a y_i + a_r y_{i+1} + b_l u_{i-1} + b u_i + b_r u_{i+1} + z.$$

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In (1), consider $N = 1$ and $d = 1$.

$$(3) \frac{dx_i}{dt} = -x_i + a_l y_{i-1} + a y_i + a_r y_{i+1} + b_l u_{i-1} + b u_i + b_r u_{i+1} + z.$$

Consider the stationary solutions,

$$(4) 0 = -x_i + a_l y_{i-1} + a y_i + a_r y_{i+1} + b_l u_{i-1} + b u_i + b_r u_{i+1} + z.$$

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- Mosaic patterns with $B = 0$:

$$y_i = 1 \Leftrightarrow (a - 1) + z + (a_l y_{i-1} + a_r y_{i+1}) > 0.$$

$$y_i = -1 \Leftrightarrow (a - 1) - z - (a_l y_{i-1} + a_r y_{i+1}) > 0.$$

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- Mosaic patterns with $B = 0$:

$$y_i = 1 \Leftrightarrow (a - 1) + z + (a_l y_{i-1} + a_r y_{i+1}) > 0.$$

$$y_i = -1 \Leftrightarrow (a - 1) - z - (a_l y_{i-1} + a_r y_{i+1}) > 0.$$

- Mosaic patterns with $B \neq 0$:

$$y_i = 1 \Leftrightarrow (a - 1) + z > -(a_l y_{i-1} + a_r y_{i+1} + b_l u_{i-1} + b u_i + b_r u_{i+1}).$$

$$y_i = -1 \Leftrightarrow (a - 1) - z > (a_l y_{i-1} + a_r y_{i+1} + b_l u_{i-1} + b u_i + b_r u_{i+1}).$$

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- 1 Partition of parameters space.

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Procedures

- 1 Partition of parameters space.
- 2 Ordering matrix of all local patterns.

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Procedures

- 1 Partition of parameters space.
- 2 Ordering matrix of all local patterns.
- 3 **Transition matrix of given templates (A, z).**

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Procedures

- 1 Partition of parameters space.
- 2 Ordering matrix of all local patterns.
- 3 Transition matrix of given templates (A, z) .
- 4 **Patterns generated by (A, z) (SFT: subshift of finite type).**

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One-layer CNN without input ($B = 0$)

Procedures

- 1 Partition of parameters space.
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- 4 Patterns generated by (A, z) (SFT: subshift of finite type).
- 5 **Spatial entropy.**

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- 5 Spatial entropy.
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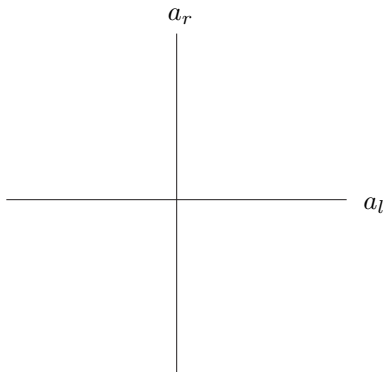
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(I) Partition of parameters space (a_l, a_r, a, z)

1. Sign of parameters:



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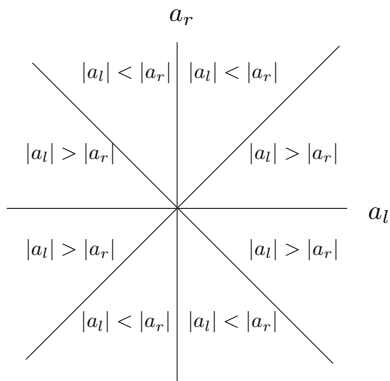
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2. Length of parameters:



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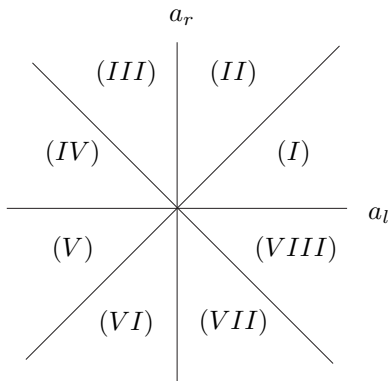
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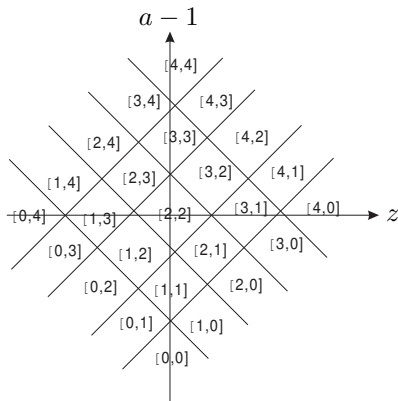
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4. Relations between a, z and other parameters $[m, n]_{(J)}$:

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(II) Ordering matrix of local patterns

$$\mathbb{X}_{3 \times 1} = \begin{array}{c} \boxed{00} \\ \boxed{01} \\ \boxed{10} \\ \boxed{11} \end{array} \left[\begin{array}{cc} \boxed{00} & \boxed{01} \\ \boxed{000} & \boxed{001} \\ \emptyset & \emptyset \\ \boxed{100} & \boxed{101} \\ \emptyset & \emptyset \end{array} \right] \begin{array}{cc} \boxed{10} & \boxed{11} \\ \emptyset & \emptyset \\ \boxed{010} & \boxed{011} \\ \emptyset & \emptyset \\ \boxed{110} & \boxed{111} \end{array}$$

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(III) Transition matrix

Given (A, z) , the local patterns $\mathcal{B} = \mathcal{B}((A, z))$.

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(III) Transition matrix

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On region $[3, 2]_{(I)}$,

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(III) Transition matrix

Given (A, z) , the local patterns $\mathcal{B} = \mathcal{B}((A, z))$.

Example:

On region $[3, 2]_{(I)}$,

$$\mathcal{B} = \{000, 001, 111, 110, 011\}.$$

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(III) Transition matrix

Given (A, z) , the local patterns $\mathcal{B} = \mathcal{B}((A, z))$.

Example:

On region $[3, 2]_{(I)}$,

$$\mathcal{B} = \{000, 001, 111, 110, 011\}.$$

The **transition matrix**

$$(5) \quad \mathbb{T} \equiv \mathbb{T}(A, z) = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}.$$

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Given (A, z) , the local patterns $\mathcal{B} = \mathcal{B}((A, z))$.

Example:

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$$(5) \quad \mathbb{T} \equiv \mathbb{T}(A, z) = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}.$$

\implies **subshift of finite type** of $\{0, 1\}^{\mathbb{Z}^1}$.

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(IV) Subshift of finite type

The same region as last example,

$G = (\mathcal{V}(G), \mathcal{E}(G))$, where

$$\mathcal{V}(G) = \{v_1, v_2, v_3, v_4\} = \{00, 01, 10, 11\},$$

$$\mathcal{E}(G) = \{e_{ij} \mid 1 \leq i, j \leq 4, t_{ij} = 1\}.$$

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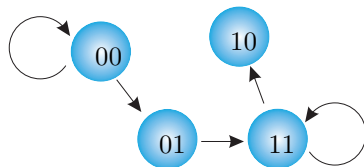
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(IV) Subshift of finite type

The same region as last example,
 $G = (\mathcal{V}(G), \mathcal{E}(G))$, where

$$\mathcal{V}(G) = \{v_1, v_2, v_3, v_4\} = \{00, 01, 10, 11\},$$

$$\mathcal{E}(G) = \{e_{ij} \mid 1 \leq i, j \leq 4, t_{ij} = 1\}.$$



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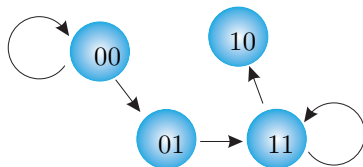
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(IV) Subshift of finite type

The same region as last example,
 $G = (\mathcal{V}(G), \mathcal{E}(G))$, where

$$\mathcal{V}(G) = \{v_1, v_2, v_3, v_4\} = \{00, 01, 10, 11\},$$

$$\mathcal{E}(G) = \{e_{ij} \mid 1 \leq i, j \leq 4, t_{ij} = 1\}.$$



$\mathbb{T} = \mathbb{T}(A, z)$: transition matrix of $G = G(A, z)$.

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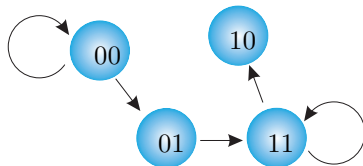
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(IV) Subshift of finite type

The same region as last example,
 $G = (\mathcal{V}(G), \mathcal{E}(G))$, where

$$\mathcal{V}(G) = \{v_1, v_2, v_3, v_4\} = \{00, 01, 10, 11\},$$

$$\mathcal{E}(G) = \{e_{ij} \mid 1 \leq i, j \leq 4, t_{ij} = 1\}.$$



$\mathbb{T} = \mathbb{T}(A, z)$: transition matrix of $G = G(A, z)$.

$$\begin{aligned} \Sigma_n(A, z) &= \{\text{patterns of length } n\} \\ &= \{e_{i_1 i_2} e_{i_2 i_3} \cdots e_{i_{n-2} i_{n-1}} \mid t_{i_k i_{k+1}} = 1, 1 \leq k \leq n-2\}. \end{aligned}$$

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(V) Spatial entropy

Given $(A, z) \Rightarrow \mathcal{B}(A, z) \Rightarrow \mathbb{T}$

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(V) Spatial entropy

Given $(A, z) \Rightarrow \mathcal{B}(A, z) \Rightarrow \mathbb{T}$

$\Gamma_{n \times 1}$: number of admissible patterns on $\mathbb{Z}_{n \times 1}$
 $\Rightarrow \Gamma_{n \times 1} = |\mathbb{T}^{n-2}|, \quad \forall n \geq 3$

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(V) Spatial entropy

Given $(A, z) \Rightarrow \mathcal{B}(A, z) \Rightarrow \mathbb{T}$

$\Gamma_{n \times 1}$: number of admissible patterns on $\mathbb{Z}_{n \times 1}$
 $\Rightarrow \Gamma_{n \times 1} = |\mathbb{T}^{n-2}|, \quad \forall n \geq 3$

Spatial entropy

$$h((A, z)) \equiv \lim_{n \rightarrow \infty} \frac{\log \Gamma_{n \times 1}}{n}$$

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(V) Spatial entropy

Given $(A, z) \Rightarrow \mathcal{B}(A, z) \Rightarrow \mathbb{T}$

$\Gamma_{n \times 1}$: number of admissible patterns on $\mathbb{Z}_{n \times 1}$
 $\Rightarrow \Gamma_{n \times 1} = |\mathbb{T}^{n-2}|, \quad \forall n \geq 3$

Spatial entropy

$$\begin{aligned} h((A, z)) &\equiv \lim_{n \rightarrow \infty} \frac{\log \Gamma_{n \times 1}}{n} \\ &= \lim_{n \rightarrow \infty} \frac{\log |\mathbb{T}^{n-2}|}{n} = \log \rho(\mathbb{T}), \end{aligned}$$

where $\rho(\mathbb{T})$ is the maximum eigenvalue of \mathbb{T} .

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(V) Spatial entropy

Given $(A, z) \Rightarrow \mathcal{B}(A, z) \Rightarrow \mathbb{T}$

$\Gamma_{n \times 1}$: number of admissible patterns on $\mathbb{Z}_{n \times 1}$
 $\Rightarrow \Gamma_{n \times 1} = |\mathbb{T}^{n-2}|, \quad \forall n \geq 3$

Spatial entropy

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where $\rho(\mathbb{T})$ is the maximum eigenvalue of \mathbb{T} .

$$h(\mathbb{T}) \begin{cases} > 0 : & \text{spatial chaos} \\ = 0 : & \text{pattern formation} \end{cases}$$

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Definition 2.1

The zeta function of \mathbb{T} is defined by

$$(6) \quad \zeta(t) := \exp\left(\sum_{n=1}^{\infty} \frac{p_n}{n} t^n\right),$$

where p_n is the number of periodic patterns with period n in \mathbb{Z}^1 .

Lemma 2.2

$$(7) \quad p_n = \text{tr}(\mathbb{T}^n).$$

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Definition 2.1

The zeta function of \mathbb{T} is defined by

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where p_n is the number of periodic patterns with period n in \mathbb{Z}^1 .

Theorem 2.3

$$(8) \quad \begin{aligned} \zeta(t) &= \exp\left(\sum_{n=1}^{\infty} \frac{\text{tr}(\mathbb{T}^n)}{n} t^n\right) \\ &= (\det(I - t\mathbb{T}))^{-1}. \end{aligned}$$

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- 4 **Labeled graph \implies Sofic shift.**

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- 3 Outputs of (A, B, z) and outputs of (A, B, z) with input \mathcal{U} .
- 4 Labeled graph \implies Sofic shift.
- 5 **Spatial entropy.**

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- 5 Spatial entropy.
- 6 **Zeta function.**

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➊ Sign of parameters (a_l, a_r, b_l, b, b_r) .

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(I) Partition of parameters space

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- 1 Sign of parameters (a_l, a_r, b_l, b, b_r) .
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- 2 Length of $(|a_l|, |a_r|, |b_l|, |b|, |b_r|)$.
- 3 **Relations between $(|a_l|, |a_r|, |b_l|, |b|, |b_r|)$.**

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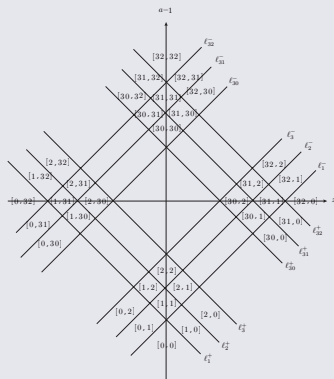
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(I) Partition of parameters space

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- 1 Sign of parameters (a_l, a_r, b_l, b, b_r) .
- 2 Length of $(|a_l|, |a_r|, |b_l|, |b|, |b_r|)$.
- 3 Relations between $(|a_l|, |a_r|, |b_l|, |b|, |b_r|)$.
- 4 Relations between a, z and other parameters
 $[m, n]_{(J)}, J = [j_1, j_2, j_3]$.



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Theorem 2.4

For $(A, B, z) \in \mathbb{R}^7$, there is a unique region $[m, n]_{(J)}$ defines the basic set of admissible local patterns $\mathcal{B}(A, B, z)$, where $0 \leq m, n \leq 32$, $J = [j_1, j_2, j_3]$, $1 \leq j_1 \leq 32$, $1 \leq j_2 \leq 120$, $1 \leq j_3 \leq 231$.

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Example 2.5

Pick $A = [a_l, a, a_r]$ and $B = [b_l, b, b_r]$ satisfying

- (1) $a_l > b_l > a_r > b > b_r > 0$;
- (2) $a_l + b_r < b_l + a_r, a_l + b > a_r + b_l + b_r$;
- (3) $a_r + b + b_r < a_l < b_l + b$;
- (4) $b_l + b_r < a_r + b, b_l > a_r + b_r, a_r > b + b_r$.

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Example 2.5

Pick $A = [a_l, a, a_r]$ and $B = [b_l, b, b_r]$ satisfying

- (1) $a_l > b_l > a_r > b > b_r > 0$;
- (2) $a_l + b_r < b_l + a_r, a_l + b > a_r + b_l + b_r$;
- (3) $a_r + b + b_r < a_l < b_l + b$;
- (4) $b_l + b_r < a_r + b, b_l > a_r + b_r, a_r > b + b_r$.

Take $R = [23, 18]$ -region in $(a - 1) - z$ plane and input $\mathcal{U} = \{- + -, - + +, + - +\}$, we have the local patterns as follows:

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Example 2.5

Pick $A = [a_l, a, a_r]$ and $B = [b_l, b, b_r]$ satisfying

- (1) $a_l > b_l > a_r > b > b_r > 0$;
- (2) $a_l + b_r < b_l + a_r, a_l + b > a_r + b_l + b_r$;
- (3) $a_r + b + b_r < a_l < b_l + b$;
- (4) $b_l + b_r < a_r + b, b_l > a_r + b_r, a_r > b + b_r$.

Take $R = [23, 18]$ -region in $(a - 1) - z$ plane and input $\mathcal{U} = \{- + -, - + +, + - +\}$, we have the local patterns as follows:

$- \ominus -$	$- \ominus -$	$- \ominus -$	$- \ominus +$
$- \boxplus -$	$- \boxplus +$	$+ \boxplus +$	$- \boxplus -$
$- \ominus +$	$- \ominus +$	$+ \ominus -$	$+ \ominus -$
$- \boxplus +$	$+ \boxplus +$	$- \boxplus -$	$- \boxplus +$
$+ \oplus +$	$+ \oplus +$	$+ \oplus +$	$+ \oplus -$
$+ \boxplus +$	$- \boxplus +$	$- \boxplus -$	$+ \boxplus +$
$+ \oplus -$	$+ \oplus -$	$- \oplus +$	$- \oplus +$
$- \boxplus +$	$- \boxplus -$	$+ \boxplus +$	$- \boxplus +$

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Motivations:

- Given $\mathcal{B} \equiv \mathcal{B}((A, B, z)) \subset \{0, 1\}^{\mathbb{Z}_{3 \times 2}}$, hope to generate $\Sigma(\mathcal{B})$.

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Motivations:

- Given $\mathcal{B} \equiv \mathcal{B}((A, B, z)) \subset \{0, 1\}^{\mathbb{Z}_{3 \times 2}}$, hope to generate $\Sigma(\mathcal{B})$.
- Consider **Output space**:

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Motivations:

- Given $\mathcal{B} \equiv \mathcal{B}((A, B, z)) \subset \{0, 1\}^{\mathbb{Z}_{3 \times 2}}$, hope to generate $\Sigma(\mathcal{B})$.
- Consider **Output space**:

$$Y_U = \{(y_i)_{i \in \mathbb{Z}} \mid \text{there exists } (u_i)_{i \in \mathbb{Z}} \text{ s.t. } (y \circ u) \in \Sigma(\mathcal{B})\},$$

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(II) Ordering matrix of $\mathbb{X}_{3 \times 2}$

Motivations:

- Given $\mathcal{B} \equiv \mathcal{B}((A, B, z)) \subset \{0, 1\}^{\mathbb{Z}_{3 \times 2}}$, hope to generate $\Sigma(\mathcal{B})$.
- Consider **Output space**:

$$Y_U = \{(y_i)_{i \in \mathbb{Z}} \mid \text{there exists } (u_i)_{i \in \mathbb{Z}} \text{ s.t. } (y \circ u) \in \Sigma(\mathcal{B})\},$$

where $(y \circ u)$ denote the $\infty \times 2$ admissible patterns

generated from \mathcal{B} , i.e.,
$$\begin{array}{c} \cdots y_{-1} y_0 y_1 \cdots \\ \cdots u_{-1} u_0 u_1 \cdots \end{array} \in \Sigma(\mathcal{B}).$$

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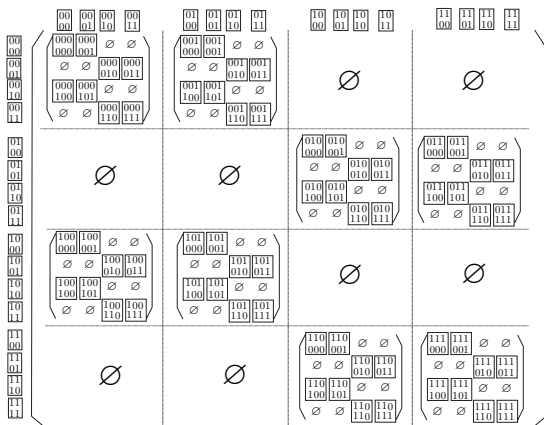
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- The ordering matrix $\mathbb{X}_{3 \times 2} = \mathbb{X}(\mathcal{B}) =$



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Remark

One can see that there is **self-similarity** on the ordering matrix of CNN with input.

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Theorem 2.6

One-layer CNN with input \mathcal{U} is a sofic shift.

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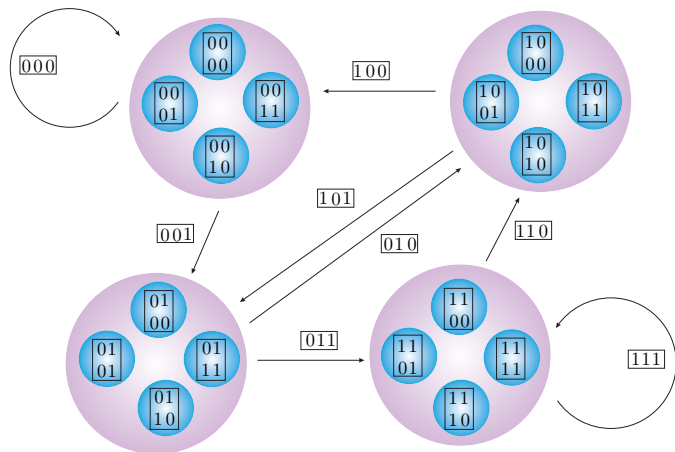
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(III) Labeled graph

Theorem 2.6

One-layer CNN with input \mathcal{U} is a sofic shift.



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(IV) Transition matrix

Example 2.7 (Continued)

$\mathbb{T}(\mathcal{B})$ can be constructed w.r.t $\mathbb{X}(\mathcal{B})$ as follows:

$$\mathbb{T} = \begin{bmatrix} T_1 & T_1 & 0 & 0 \\ 0 & 0 & 0 & T_3 \\ T_2 & 0 & 0 & 0 \\ 0 & 0 & T_1 & T_1 \end{bmatrix},$$

where $T_1 = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$, $T_2 = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ and

$$T_3 = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

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Why Sofic?

Given A , B and z , we have the basic set $(B) \equiv \mathcal{B}(A, B, z)$

① $|\mathbb{T}^{n-2}(\mathcal{B})| =$ the number of all admissible patterns in $\Sigma_{n \times 2}(\mathcal{B})$

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Given A, B and z , we have the basic set $(B) \equiv \mathcal{B}(A, B, z)$

- 1 $|\mathbb{T}^{n-2}(B)|$ = the number of all admissible patterns in $\Sigma_{n \times 2}(B)$
- 2 To generate admissible patterns of Y_U , $\mathcal{S} = \{s_{ijk}\}_{0 \leq i, j, k \leq 1}$ should be introduced to **specify** the output patterns.

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Why Sofic?

Given A , B and z , we have the basic set $(B) \equiv \mathcal{B}(A, B, z)$

- 1 $|\mathbb{T}^{n-2}(\mathcal{B})|$ = the number of all admissible patterns in $\Sigma_{n \times 2}(\mathcal{B})$
- 2 To generate admissible patterns of Y_U , $\mathcal{S} = \{s_{ijk}\}_{0 \leq i, j, k \leq 1}$ should be introduced to **specify** the output patterns.
- 3 Once

$$\mathbb{T} = \begin{bmatrix} T_1 & T_2 & 0 & 0 \\ 0 & 0 & T_3 & T_4 \\ T_5 & T_6 & 0 & 0 \\ 0 & 0 & T_7 & T_8 \end{bmatrix}$$

is constructed, let

$\mathcal{S} = \{s_{000}, s_{001}, s_{010}, s_{011}, s_{100}, s_{101}, s_{110}, s_{111}\}$, then **symbolic transition matrix** \mathbb{S} is:

$$\mathbb{S} = \begin{bmatrix} s_{000}T_1 & s_{001}T_2 & 0 & 0 \\ 0 & 0 & s_{010}T_3 & s_{011}T_4 \\ s_{100}T_5 & s_{101}T_6 & 0 & 0 \\ 0 & 0 & s_{110}T_7 & s_{111}T_8 \end{bmatrix}.$$

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Theorem 2.8

Y_U is conjugate to $X_{\mathbb{S}}$ under $\phi : Y_U \rightarrow X_{\mathbb{S}}$, where ϕ is a factor map induced by the sliding block code $\Phi(y_0y_1y_2) = s_{y_0y_1y_2}$.

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Theorem 2.8

Y_U is conjugate to X_S under $\phi : Y_U \rightarrow X_S$, where ϕ is a factor map induced by the sliding block code $\Phi(y_0y_1y_2) = sy_0y_1y_2$.

Theorem 2.9

If X and Y are shift spaces, and X is conjugate to Y under conjugacy ϕ , then

- $h(X) = h(Y)$;
- $\zeta_{\sigma_X}(X) = \zeta_{\sigma_Y}(Y)$

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Theorem 2.8

Y_U is conjugate to $X_{\mathbb{S}}$ under $\phi : Y_U \rightarrow X_{\mathbb{S}}$, where ϕ is a factor map induced by the sliding block code $\Phi(y_0y_1y_2) = s_{y_0y_1y_2}$.

Theorem 2.9

If X and Y are shift spaces, and X is conjugate to Y under conjugacy ϕ , then

- $h(X) = h(Y)$;
- $\zeta_{\sigma_X}(X) = \zeta_{\sigma_Y}(Y)$

- Thus the problem of computation the **entropy and zeta function** of Y_U is equivalent to compute the these two invariants of $X_{\mathbb{S}}$.

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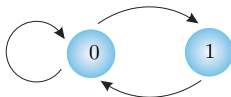
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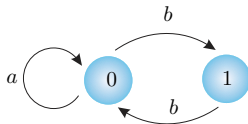
Definition 3.1

A labeled graph \mathcal{G} is a pair (G, \mathcal{L}) , where G is a graph with edge \mathcal{E} , and the labeling $\mathcal{L} : \mathcal{E} \rightarrow \mathcal{A}$ assigns to each edge e of G a label $\mathcal{L}(e)$ from the finite alphabet \mathcal{A} . The underlying graph of \mathcal{G} is G .

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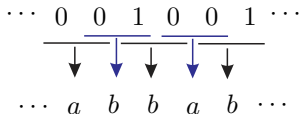
Definition 3.1

A labeled graph \mathcal{G} is a pair (G, \mathcal{L}) , where G is a graph with edge \mathcal{E} , and the labeling $\mathcal{L} : \mathcal{E} \rightarrow \mathcal{A}$ assigns to each edge e of G a label $\mathcal{L}(e)$ from the finite alphabet \mathcal{A} . The underlying graph of \mathcal{G} is G .

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- If $\zeta = \cdots e_{-1}e_0e_1 \cdots$ is a bi-infinite word in G , define the label of the walk ζ to be

$$\mathcal{L}_\infty = \cdots \mathcal{L}(e_{-1}) \mathcal{L}(e_0) \mathcal{L}(e_1) \cdots \in \mathcal{A}^{\mathbb{Z}}.$$



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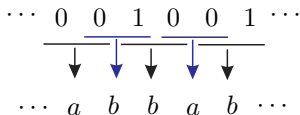
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- If $\zeta = \cdots e_{-1}e_0e_1 \cdots$ is a bi-infinite word in G , define the label of the walk ζ to be

$$\mathcal{L}_\infty = \cdots \mathcal{L}(e_{-1}) \mathcal{L}(e_0) \mathcal{L}(e_1) \cdots \in \mathcal{A}^{\mathbb{Z}}.$$



- Thus, X_G is defined,

$$X_G = \{x \in \mathcal{A}^{\mathbb{Z}} : x = \mathcal{L}_\infty(\zeta) \text{ for some } \zeta \in X_G\}.$$

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- X : shift space, $h(X) = \lim_{n \rightarrow \infty} \frac{\log |B_n(X)|}{n}$,
where $B_n(X)$ is the n -block of X .

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- X : shift space, $h(X) = \lim_{n \rightarrow \infty} \frac{\log |B_n(X)|}{n}$,
where $B_n(X)$ is the n -block of X .

- The entropy of X is the growth rate of n -block in X ,
i.e., it measures the complexity of X .

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- X : shift space, $h(X) = \lim_{n \rightarrow \infty} \frac{\log |B_n(X)|}{n}$,
where $B_n(X)$ is the n -block of X .
- The entropy of X is the growth rate of n -block in X ,
i.e., it measures the complexity of X .
- For N -layer CNN, in some region of parameter space, we
compute the entropy of the output space $h(Y_U)$,
where $Y_U = \{(y_i)_{i \in \mathbb{Z}} \mid \exists (u_i)_{i \in \mathbb{Z}} \text{ s.t. } (y \circ u) \in \Sigma(\mathcal{B})\}$

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Theorem 3.2

If X is a SFT, and \mathbb{T} is its transition matrix, then

$$h(X) = \log \rho(\mathbb{T}).$$

where $\rho(\mathbb{T})$ is the maximal eigenvalue of \mathbb{T} .

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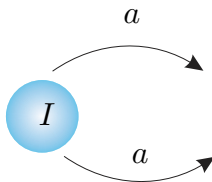
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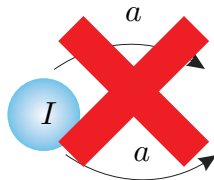
Definition 3.3

A label set $\mathcal{G} = (G, \mathcal{L})$ is right resolving if for every vertex I of G , the edge from I carry different labels.

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Definition 3.3

A label set $\mathcal{G} = (G, \mathcal{L})$ is right resolving if for every vertex I of G , the edge from I carry different labels.



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Theorem 3.4

Given Y_U , and $\mathbb{S} = (G_{\mathbb{T}}, \mathcal{L})$ is the sofic shift induced by Y_U , if \mathbb{S} is **right-resolving**, then the entropy of $X_{\mathbb{S}}$ is

$$h(X_{\mathbb{S}}) = \log \rho(\mathbb{T}).$$

where $\rho(\mathbb{T})$ is the maximal eigenvalue of \mathbb{T} .

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where $\rho(\mathbb{T})$ is the maximal eigenvalue of \mathbb{T} .

- In this case, $h(Y_U) = h(X_{\mathbb{S}}) = \log \rho(\mathbb{T})$.

Theorem 3.5

Given $\mathbb{S} = (G_{\mathbb{T}}, \mathcal{L})$ is a labeled graph which is not right resolving, then there is a sofic shift $\mathcal{H} = (G_{\mathbb{H}}, \mathcal{L})$ which is right resolving that is conjugate to $X_{\mathbb{S}}$, i.e., $X_{\mathbb{S}} = X_{\mathcal{H}}$.

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Theorem 3.5

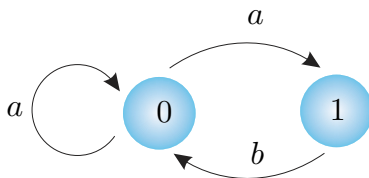
Given $\mathbb{S} = (G_{\mathbb{T}}, \mathcal{L})$ is a labeled graph which is not right resolving, then there is a sofic shift $\mathcal{H} = (G_{\mathbb{H}}, \mathcal{L})$ which is right resolving that is conjugate to $X_{\mathbb{S}}$, i.e., $X_{\mathbb{S}} = X_{\mathcal{H}}$.

- In this case $h(Y_U) = h(X_{\mathbb{S}}) = h(X_{\mathcal{H}}) = \log \rho(\mathbb{H})$.
- The method for constructing $\mathcal{H} = (G_{\mathbb{H}}, \mathcal{L})$ is called “Subset Construction”.

Example 3.6

For a sofic shift with the sign matrix is

$$B = \begin{bmatrix} a & a \\ b & \emptyset \end{bmatrix}, \quad A = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$$



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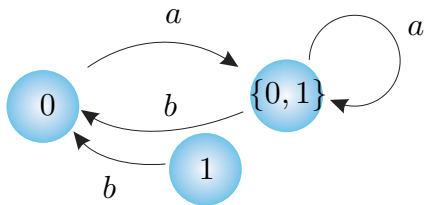
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Introduce a new symbol $\{0, 1\}$, and a new symbolic adjacency matrix C indexed by $\{0, 1, \{0, 1\}\}$ as

$$C = \begin{bmatrix} a & b & \emptyset \\ a & \emptyset & \emptyset \\ \emptyset & b & \emptyset \end{bmatrix}$$



Thus in this case C is right resolving, and $X_{G_B} \simeq X_{G_C}$.

- Such construction is not unique, all of them are conjugate.

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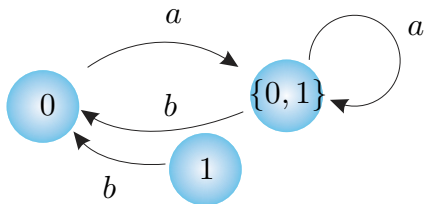
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Introduce a new symbol $\{0, 1\}$, and a new symbolic adjacency matrix C indexed by $\{0, 1, \{0, 1\}\}$ as

$$C = \begin{bmatrix} a & b & \emptyset \\ a & \emptyset & \emptyset \\ \emptyset & b & \emptyset \end{bmatrix}$$



Thus in this case C is right resolving, and $X_{G_B} \simeq X_{G_C}$.

- Such construction is not unique, all of them are conjugate.
- **Minimal subset construction**

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For computation the entropy of $\mathcal{G}_B = (G_A, \mathcal{L})$, define the transition matrix of C by

$$D = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix},$$

we have

$$h(X_{\mathcal{G}_B}) = h(X_{\mathcal{G}_C}) = \log \rho(D) = \log \frac{1 + \sqrt{5}}{2}.$$

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Definition 3.7

Let (M, ϕ) be a dynamical system for which $p_n(\phi) < \infty$ for all $n \geq 1$. The zeta function $\zeta_\phi(t)$ is defined as

$$\zeta_\phi(t) = \exp\left(\sum_{n=1}^{\infty} \frac{p_n(\phi)}{n} t^n\right).$$

Theorem 3.8

Let A be an $r \times r$ nonnegative integer matrix, $\chi_A(t)$ is characteristic polynomial, then

$$\zeta_{\sigma_A}(t) = \frac{1}{t^r \chi_A(t^{-1})} = \frac{1}{\det(Id - tA)}$$

Thus the zeta function of a SFT is the reciprocal of a polynomial.

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Notations:

$\mathcal{G} = (G, \mathcal{L})$: right resolving labeled graph

r : the number of vertices in G

$\mathcal{V} = \{1, \dots, r\}$

B : the symbolic transition matrix of $X_{\mathcal{G}}$

A : obtained from B by letting all the symbol equal to 1

① $F = \{f_1 \cdots f_j\}$

π : permutation act on F

i.e., $\pi(F) = (f_{i_1}, \dots, f_{i_j})$ with $\pi(f_k) = f_{i_k}$ for $k = 1, \dots, j$.

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π : permutation act on F

i.e., $\pi(F) = (f_{i_1}, \dots, f_{i_j})$ with $\pi(f_k) = f_{i_k}$ for $k = 1, \dots, j$.

② Define the

$$\text{sgn}(\pi) = \begin{cases} 1 & \text{if } \pi \text{ is even} \\ -1 & \text{if } \pi \text{ is odd} \end{cases}$$

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Signed subset matrices:

1 Construct \mathcal{G}_j with $\{\pm a : a \in \mathcal{A}\}$, where $1 \leq j \leq r = |\mathcal{V}|$.

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Signed subset matrices:

- 1 Construct \mathcal{G}_j with $\{\pm a : a \in \mathcal{A}\}$, where $1 \leq j \leq r = |\mathcal{V}|$.
- 2 $|\mathcal{V}_j| = \binom{r}{j}$: the number of vertices of \mathcal{G}_j .

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- 3 If there is a edge a sent $\mathcal{I} = \{I_1, \dots, I_j\}$ to $\mathcal{J} = \{J_1, \dots, J_j\}$, then there is a labeling a from \mathcal{I} to \mathcal{J} in \mathcal{G}_j if (J_1, \dots, J_j) is even, otherwise, label it by $-a$.

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Signed subset matrices:

- 1 Construct \mathcal{G}_j with $\{\pm a : a \in \mathcal{A}\}$, where $1 \leq j \leq r = |\mathcal{V}|$.
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- 4 We get \mathcal{G}_j, B_j and A_j .

Theorem 3.9

Let \mathcal{G} be a right resolving labeled graph with r vertices, and let A_j be its j th sign subset matrix. Then

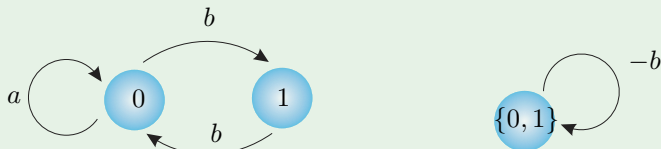
$$\zeta_{\sigma_{\mathcal{G}}}(t) = \prod_{j=1}^r [\det (Id - tA_j)]^{(-1)^j}$$

- Thus the zeta function for a sofic shift is a *rational function*.

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Example 3.10 (Even Shift)

If $\mathcal{G} = (G_A, \mathcal{L})$, with $B = \begin{bmatrix} a & b \\ b & \emptyset \end{bmatrix}$ and $A = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$, then $\mathcal{G}_1 = \mathcal{G}$. Moreover, \mathcal{G}_2 can be constructed with $B_2 = [-b]$ and $A_2 = [-1]$.



Thus, the zeta function can be computed as

$$\zeta_{\sigma_{\mathcal{G}}}(t) = \frac{1+t}{1-t-t^2}.$$

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Theorem 3.11

Given A, B, z , and \mathcal{U} , let $\tilde{\mathbb{T}} = \mathbb{T}((A, B, z))$,
 $\mathbb{T} = \mathbb{T}((A, B, z); \mathcal{U}) \in \mathcal{M}_{16}(\mathbb{R})$ and $\mathbb{U} = \mathbb{T}(\mathcal{U}) \in \mathcal{M}_4(\mathbb{R})$ be the
 transition matrices, then

$$(9) \quad \mathbb{T} = \tilde{\mathbb{T}} \circ (E_4 \otimes \mathbb{U}),$$

where \circ and \otimes are the Hadamard product and Kronecker
 product, resp., $E_4 = (e_{ij}) \in \mathcal{M}_4(\mathbb{R})$ with $e_{ij} = 1$ for all i, j .

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Example 3.12 (Continued)

Same example as before, the transition matrix is

$$\mathbb{T} = \begin{bmatrix} T_1 & T_1 & 0 & 0 \\ 0 & 0 & 0 & T_3 \\ T_2 & 0 & 0 & 0 \\ 0 & 0 & T_1 & T_1 \end{bmatrix},$$

where $T_1 = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$, $T_2 = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ and

$$T_3 = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

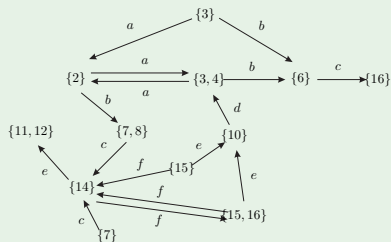
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Example 3.12 (Continued)

Therefore, we have

$$\mathbb{S} = \begin{bmatrix} s_{000}T_1 & s_{001}T_1 & 0 & 0 \\ 0 & 0 & 0 & s_{011}T_3 \\ s_{100}T_2 & 0 & 0 & 0 \\ 0 & 0 & s_{110}T_1 & s_{111}T_1 \end{bmatrix}.$$

This sofic is not right resolving. Use subset construction:



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Example 3.12 (Continued)

New right resolving sofic shift can be obtained as

$$\mathbb{H} = \begin{bmatrix} 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 \end{bmatrix},$$

then $h((A, B, z)) = \log \lambda > 0$

where λ is the maximal eigenvalue of $t^6 - 2t^4 + t^2 - 1 = 0$.

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Example 3.12 (Continued)

For the computation of zeta function, we should construct the k -th sign subset matrices A_k of \mathbb{H} .

$$A_1 = \mathbb{H}, A_2 = \begin{bmatrix} 0 & -1 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix},$$

and $A_3 = \dots = A_{12} = 0$, then

$$\zeta_{\sigma_{\mathbb{H}}} = \frac{(t+1)^2}{1 - 2t^2 + t^4 - t^6}.$$

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Theorem 3.13

Given (A, B, z) , then

- 1 If $B = 0$, then $\mathcal{B}(A, B, z)$ and transition matrix \mathbb{T} can be uniquely defined and

$$\Sigma(\mathcal{B}(A, B, z)) = X_{\mathbb{T}}.$$

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Theorem 3.13

Given (A, B, z) , then

- ① If $B = 0$, then $\mathcal{B}(A, B, z)$ and transition matrix \mathbb{T} can be uniquely defined and

$$\Sigma(\mathcal{B}(A, B, z)) = X_{\mathbb{T}}.$$

- ② If $B \neq 0$, $\mathcal{B}(A, B, z)$ and transition matrix \mathbb{T} can be uniquely defined. Let $\mathcal{S} = \{s_i\}_{i \in I}$ and construct \mathbb{S} , then

$$Y_U = X_{\mathbb{S}},$$

where

$$Y_U = \{(y_i)_{i \in \mathbb{Z}} \mid \text{there exists } (u_i)_{i \in \mathbb{Z}} \text{ s.t. } (y \circ u) \in \Sigma(\mathcal{B})\}.$$

and $\mathbb{S} = (G_{\mathbb{T}}, \mathcal{S})$ is the sofic shift with underlying graph $G_{\mathbb{T}}$ and labeling by \mathcal{S} .

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Equations

$$(10) \quad \frac{dx_i^{(n)}}{dt} = -x_i^{(n)} + \sum_{|k| \leq d} a_k y_{i+k}^{(n)} + \sum_{|k| \leq d} b_k u_{i+k}^{(n)} + z^{(n)},$$

where $u_i^{(n)} = y_i^{(n-1)}$ for $1 \leq n \leq N$, and $u_i^{(0)} = u_i$ for $i \in \mathbb{Z}$.

Questions

For N -layer CNN with input:

- **Relation between i -th and $(i + 1)$ -th layer?**

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where $u_i^{(n)} = y_i^{(n-1)}$ for $1 \leq n \leq N$, and $u_i^{(0)} = u_i$ for $i \in \mathbb{Z}$.

Questions

For N -layer CNN with input:

- **Relation between i -th and $(i + 1)$ -th layer?**
- **Entropy?**

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MCNN: N-layer CNN with input

Equations

$$(10) \quad \frac{dx_i^{(n)}}{dt} = -x_i^{(n)} + \sum_{|k| \leq d} a_k y_{i+k}^{(n)} + \sum_{|k| \leq d} b_k u_{i+k}^{(n)} + z^{(n)},$$

where $u_i^{(n)} = y_i^{(n-1)}$ for $1 \leq n \leq N$, and $u_i^{(0)} = u_i$ for $i \in \mathbb{Z}$.

Questions

For N -layer CNN with input:

- Relation between i -th and $(i + 1)$ -th layer?
- Entropy?
- Zeta function?

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Denote the parameters spaces and admissible local patterns of each layer by

$$(11) \quad \mathcal{P}^{(i)} = \{(A^{(i)}, B^{(i)}, z^{(i)})\}, \mathcal{B}^{(i)}(A^{(i)}, B^{(i)}, z^{(i)}),$$

for $1 \leq i \leq N$. Let

$$(12) \quad \begin{aligned} A &= (A^{(1)}, A^{(2)}, \dots, A^{(N)}), \\ B &= (B^{(1)}, B^{(2)}, \dots, B^{(N)}), \\ \mathcal{P} &= (\mathcal{P}^{(1)}, \mathcal{P}^{(2)}, \dots, \mathcal{P}^{(N)}). \end{aligned}$$

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Theorem 4.1

There exists $K \in \mathbb{N}$ and unique set of open subregions $\{P_k\}_{k=1}^K$ of \mathcal{P} such that

$$(i) \quad \mathcal{P} = \bigcup_{k=1}^K \bar{P}_k.$$

$$(ii) \quad P_k \cap P_j = \emptyset \text{ for } k \neq j.$$

$$(iii) \quad \mathcal{B}(A, B, z) = \mathcal{B}(A', B', z') \Leftrightarrow \\ (A, B, z), (A', B', z') \in P_k \text{ for some } k.$$

- Linear Separation Theorem.
- Thus, $\mathcal{B}(A^{(i)}, B^{(i)}, z^{(i)})$ for N-layer MCNN with input can be uniquely specified.

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Transition matrix for $N = 2$

Given $(A^{(1)}, B^{(1)}, z^{(1)})$, $(A^{(2)}, B^{(2)}, z^{(2)})$ and \mathcal{U} , we obtain the admissible local patterns $\mathcal{B}^{(1)}$, $\mathcal{B}^{(2)}$ and the transition matrices \mathbb{T}_1 , \mathbb{T}_2 , \mathbb{U} .

Denote the transition matrix of $\mathcal{B}((A, B, z); \mathcal{U}) = \mathcal{B}^{(2)} * \mathcal{B}^{(1)}$ by \mathbb{T} .

Theorem 4.2

$$\mathbb{T} = (\mathbb{T}_2 \otimes E_4) \circ (E_4 \otimes (\mathbb{T}_1 \circ (E_4 \otimes \mathbb{U}))).$$

Theorem 4.3

*Two-layer CNN is a sofic shift generated by labeled graph $(\mathcal{B}^{(2)} * \mathcal{B}^{(1)}, \mathcal{L})$.*

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Theorem 4.4

If $N \geq 2$, then given $(A^{(i)}, B^{(i)}, z^{(i)})$ for $i = 1, \dots, N$, then

- 1 The transition matrix of $(i + 1)$ -layer associate with the i -th layer can be defined

$$\mathbb{T}_{i+1,i} = (\mathbb{T}_{i+1} \otimes E_4) \circ (E_4 \otimes \mathbb{T}_i).$$

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- 2 The transition matrix of $(i + 1)$ -layer associate with the first i -layers can be recurrence defined

$$\hat{\mathbb{T}}_{i+1} = (\mathbb{T}_{i+1} \otimes E_{4^i}) \circ (E_4 \otimes \hat{\mathbb{T}}_i).$$

where $\hat{\mathbb{T}}_1 = \mathbb{T}_1$.

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where $\hat{\mathbb{T}}_1 = \mathbb{T}_1$.

- 3 Introduce $\mathcal{S} = \{s_{ijk}\}_{0 \leq i,j,k \leq 1}$, thus \mathbb{S}_{i+1} can be recurrently defined from \mathbb{T}_{i+1} .

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- Thus, we need to study the dynamics of convolution of N -coupled sofic shifts, i.e.,

$$\Phi_N * \Phi_{N-1} * \cdots * \Phi_1$$

where Φ_i is a sofic shift for all $i = 1, \dots, N$.

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$$\Phi_N * \Phi_{N-1} * \cdots * \Phi_1$$

where Φ_i is a sofic shift for all $i = 1, \dots, N$.

- MCNN is a nature motivation for the convolution of “ N -coupled sofic shifts”.

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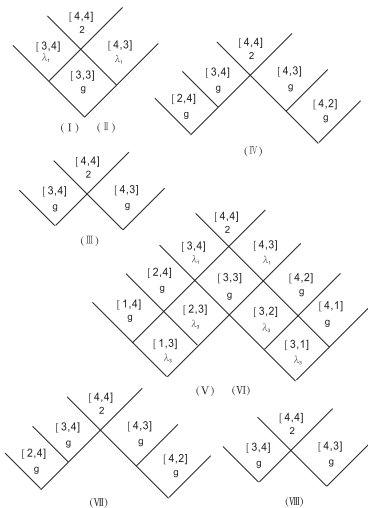
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- Symmetric of entropy for 1-D CNN without input.



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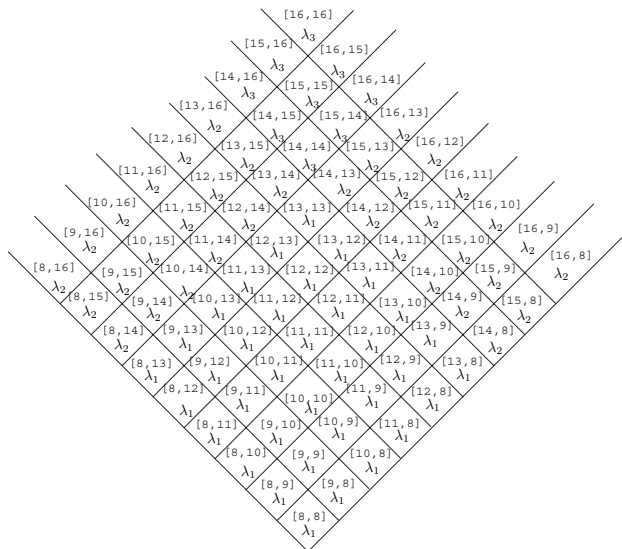
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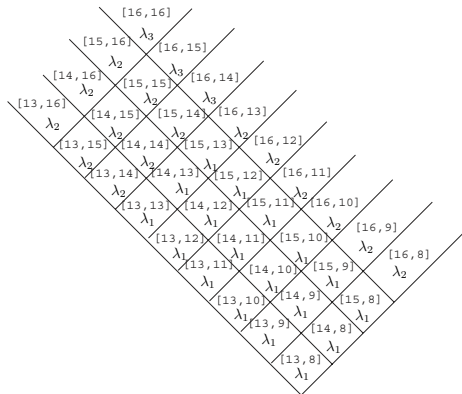
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- Nonsymmetric for N-Layer CNN with input with $N \geq 2$.



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- 1 Two-dimensional MCNN.
 - 1 Equivalent to more symbol problem.

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- 1 **Two-dimensional MCNN.**
 - 1 Equivalent to more symbol problem.
 - 2 Use connecting and trace operators in 2-dim patterns generation problem to estimate lower bound and upper bound of output entropy.

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- 1 **Two-dimensional MCNN.**
 - 1 Equivalent to more symbol problem.
 - 2 Use connecting and trace operators in 2-dim patterns generation problem to estimate lower bound and upper bound of output entropy.
- 2 **Entropy formula and Zeta function formula for MCNN:**

$$h(Y_U^{(i)}) = h(Y_U^{(i-1)}) * \dots * h(Y_U^{(1)})? \text{ for } 1 \leq i \leq N$$

$$\zeta_\sigma(Y_U^{(i)}) = \zeta_\sigma(Y_U^{(i-1)}) * \dots * \zeta_\sigma(Y_U^{(1)})? \text{ for } 1 \leq i \leq N$$

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- 1 Chua L.-O, and Yang L. [1988] "Cellular neural networks: Theory", *IEEE Trans. Circuits Systems.* **35**, 1257-1290.

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- 2 Hsu C.-H., Juang J., Lin S.-S., & Lin W.-W [2000] "Cellular neural networks: local patterns for general template", *International J. of Bifurcation and Chaos* **10**, 1645-1659.

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